

# GSM/GPRS/GPS Tracker GV100 User Manual

TRACGV100UM001

**Revision: 1.00** 



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# 0. Revision history

Revision	Date	Author	Description of change
1.00	2009-10-15	Edwin Peng	Initial

# 1. Introduction

The GV100 is a powerful GPS Locator designed for vehicle tracking or asserts tracking. With superior receiving sensitivity, fast TTFF (Time to First Fix) and Quad-Band GSM frequencies 850/900/1800/1900, its location can be monitored in real time or periodically tracked by a backend server or other specified terminals. The GV100 has multiple input/output interfaces which can be used for monitoring or controlling external devices. Based on the integrated @Track protocol, the GV100 can communicate with a backend server through the GPRS/GSM network to transfer reports of Emergency, Geo-fence boundary crossings, Lower Battery or scheduled GPS position along with many other useful functions. Users can also use GV100 to monitor the status of a vehicle and control the vehicle with its onboard relay output. System Integrators can easily setup their tracking systems based on the full-featured @Track protocol.

## 1.1. Reference

SN	Document name	Remark
[1]	GV100 @Track Air Interface Protocol v1 00.PDF	The air protocol interface between
		GV100 and backend server.
[2]		

#### **1.2.** Terms and abbreviations

Abbreviation	Description



# 2. Product Overview

# 2.1. Appearance



# 2.2. Parts List

Name	Picture
GV100 Locater	AVL GPS Traver
Power Cable with fuse	
I/O cable	

GV100 User manual

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Steel Piece	
GPS Antenna	
GSM Antenna	-Q_
12V DC power supply (Optional)	
USB-232 data cable (Optional)	
Relay (Optional)	

# 3. Interface Description And Installation Guide

# 3.1. SIM Card Interface

To install the SIM card

**Step 1:** Press the yellow button on the right side of SIM card slot to eject the SIM card holder.



- **Step 2:** Put the SIM card on the SIM card holder.
- **Step 3:** Install the SIM card holder to SIM card slot.



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## **3.2.** Antenna Interface

#### 3.2.1. Install Antennas

There are two SMA antenna connectors on GV100, one for GPS and another for GSM. Please find the GSM antenna and GSM antenna in package box. Install them to the correct SMA connector like following.







#### 3.2.2. GPS antenna specification

GPS antenna:	Frequency: 1575.42MHz
Bandwidth:	>5MHz
Beamwidth:	>120 deg
Supply voltage:	3.3V
Polarization:	RHCP or Linear
Gain:	Passive: 0dBi minimum
	Active: 15dB
Impedance:	<b>50</b> Ω
VSWR:	< 2
Noise figure:	<3

#### 3.2.3. GSM antenna specification

Frequency and bandwidth	GSM850: 824MHz to 894MHz;
	EGSM900: 880MHz to 960MHz;
	DCS1800: 1710MHz to 1885MHz;
	PCS1900: 1850MHz to 1990MHz;
Direction:	Omnidirection;
Gain:	Passive: >0dBi;
Impedance:	50Ω;
VSWR:	<4;
Efficient:	GSM850: >40%;
	EGSM900: >40%;
	DCS1800: >30%;
	PCS1900: >30%;

#### **3.3.** Power Interface

# **3.3.1.** Power Interface definition

There are four Pins on power connector:



Index	Color of power cable	Description	<b>Recommended Function</b>
1	Red	Power (+8V ~ 32V)	Power
2	Black	Ground	Ground
3	Yellow	Input 1 (Digital, Positive Trigger)	Ignition Key Detect
4	White	Digital Output 1 (Negative Trigger)	

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#### **3.3.2.** Power connection

The input voltage range of GV100 is 8V to 32V DC and can be connected to vehicle's battery directly (12V or 24V DC). Please install the power like following.



#### 3.3.3. Ignition Detect

The PIN 3 of power connector is Input 1 (Digital, Positive trigger). Its electrical conditions are:

Logical State	Electrical State
Active	5.0V to 32V
Inactive	0V to 3V or Open

It is strongly recommended to connect this pin to ignition key to support the power saving function when the vehicle is off. Please note input 1 does not have interrupt and the recommended sample rate is 3 seconds.



#### 3.3.4. Ignition Control

The PIN 4 of power connector is Output 1 (Digital, Negative trigger). It is Open-Drain type with no internal pull-up resistor which also be used to control a relay. It means that the user has to provide a pull-up resistor or a relay coil to any positive voltage (32V max.) to detect an inactive output by voltage. It can drive a continuous current of 0.2A.

Logical State	Electrical State
Active	<1.5V, max current is 0.2A
Inactive	Open or the pull-up voltage
	(max 32V)

User can use this pin to control a relay output. An example to control the ignition key is showed in following figure. Please refer to chapter 3.4.5 for the detail information on how to drive a relay with digital output.



## 3.4. I/O Interface



There are several inputs and outputs on I/O cable and the definition are:

Index	Color on I/O cable	Description	<b>Recommended Function</b>
1	White	Input 2 (Digital, Positive Trigger)	
2	Black	Input 3 (Digital, Positive Trigger, With interrupt)	
3	Brown	Input 4 (Digital, Negative Trigger, With interrupt)	Panic Button
4	Yellow	Input 5 (Digital, Negative Trigger)	
5	Gray	Input 6 (Analog, Input voltage range : 0 – 28 V)	
6	Purple	Digital Output 2 (Negative Trigger)	
7	Red	Digital Output 3 (Negative Trigger)	
8	Green	Digital Output 4 (Negative Trigger)	
9	Orange		
10	Blue	Digital Output 5 (Built in Relay)	

#### 3.4.1. Electrical conditions for digital inputs

For negative trigger inputs the electrical conditions are:

Logical State	Electrical State
Active	0V to 0.8V
Inactive	1.7V to 32V or Open

For positive trigger inputs the electrical conditions are:

Logical State	Electrical State
Active	5.0V to 32V
Inactive	0V to 3V or Open

The example connections are showed in following figure:



Example connection for Positive Trigger digital inputs



Example connection for Negative Trigger digital inputs

#### 3.4.2. Digital Input without Interrupt

Input 2 and input 5 are digital inputs which do not have interrupt. The sample rate for these two digital inputs is 100ms to 25 seconds. The recommend sample rate is 3 seconds. Please note the high sample rate will also result in high power consumption. Input 2 is positive trigger and Input 5 is negative trigger.

#### 3.4.3. Digital Input with Interrupt

Input 3 and input 4 are digital inputs which have interrupt. Input 3 is positive trigger and input 4 is negative trigger.

The example connections are same as showed in chapter 3.4.1.

Input 4 is also recommended to support panic button function and the connection is showed as following.



#### 3.4.4. Analog Input

The pin 5 of I/O cable is used for analog to digital converter. The input voltage range is 0V to 28V and can tolerant 32V voltage. Please note it is an average value based on the sample rate of 10 seconds, which means the bust on voltage input will not be detected.

#### 3.4.5. Digital Output

The outputs are Open-Drain type with no internal pull-up resistor which also be used to control a relay. It means that the user has to provide a pull-up resistor or a relay coil to any positive voltage (32V max.) to detect an inactive output by voltage. Each output can drive a continuous current of 0.2A.

#### The electrical conditions are:

Logical State	Electrical State	
Active	<1.5V, max current is 0.2A	
Inactive	Open or the pull-up voltage	
	(max 32V)	

The outputs are used for cutting/restoring GND. The example connections are:



The example connection to drive a LED



#### The example connection to drive a Relay

If the digital output is used to drive a relay, a catch diode is showed across the relay coil, this is necessary to prevent damage to the digital output when the relay is turned off. Many modern relays come with this diode pre-installed internal to the relay itself. If the relay has this diode, insure the proper relay polarity connected is used. If this diode is not internal, it should be added externally. A common diode such as a 1N4004 will work in most circumstances.

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#### 3.4.6. Digital Output with Built-in Relay

The build in relay output is Open-Drain type with no internal pull-up resistor. It means that the user has to provide a pull-up resistor to any positive voltage to detect an inactive output by voltage. The switch capacity of the relay contact is 60W, so it can drive a continuous current of 2A at the input voltage of 30V and 1.85A at the input voltage of 32V.

#### The electrical conditions are:

Logical State	Electrical State
Active	0V
Inactive	Open or the pull-up voltage
	(max 32V)

The output is used for cutting/restoring GND. It can be directly drive a LED and the example connection is showed as following.



#### 3.5. Audio Interface

The audio connector is designed to connect a non-balanced hands-free audio system. It is designed to use a 2.5mm stereo plug with the following configuration, please pay attention to the common GND ,this common GND is used only for audio ground, it should not used as a power ground. The speaker interface can be connected to a 320hm speaker or an audio amplifier which drive a louder speaker. The electret microphone is recommended.



# Microphone input characteristics

Parameter	Min	Тур	Max	Unit
Working Voltage	1.0	1.5	2.0	V
Working Current	200		500	uA
External		2.2		k Ohm
Microphone Load				
Resistance				

# Speaker output characteristics

Parameter	Min	Тур	Max	Unit
Speaker load	16	32		Ohm
Resistance				
Speaker output	0		2.4	Vpp
level				
Maxim driving			50	mA
current limit of				
speaker				

## 3.6. RS232 Interface

An RS232 interface has been implemented on GV100 and it can be used to configure the runtime parameters of GV100.



# RS232 DB-9 Connector Pin Description (PC side)

Pin Index	Signal Name	Signal Description
1	CD	Carrier Detect
2	RXD	Receive Data
3	TXD	Transmit Data
4	DTR	Data Terminal Ready
5	GND	Ground
6	None	None
7	RTS	Request To Send
8	CTS	Clear To Send
9	RI	Ring Indicator

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## **3.7. Fasten The Device**

Please use the steel piece and screw to fasten the device.



# 4. Compliance

This transmitter is using outdoor antennas that operate at 20cm or more from nearby persons. Section 15.105 (b)

Note: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the

instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation.

If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

--Reorient or relocate the receiving antenna.

--Increase the separation between the equipment and receiver.

--Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.

--Consult the dealer or an experienced radio/TV technician for help.

# FCC/Industry Canada Notice

#### Statement according to FCC part 15.105

#### NOTE:

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation.

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- · Reorient or relocate the receiving antenna.
- · Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

#### Statement according to FCC part 15.21

Modifications not expressly approved by Westermo could void the user's authority to operate the equipment.

#### Statement according to FCC part 15.19

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) this device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

# 5 Approvals

EMC: FCC part 2, 15, 22 and 24

Network: PTCRB

Safety: UL 60950-1, CSA 22.2 No 60950-1-03 (first edition)





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