# **ZigBee OEM Module**

**ProBee-ZE20S** 

**User Guide** 

Sena Technologies, Inc.

**Rev 1.0.2** 

ProBee-ZE20S User Guide Rev.1.0.2 2

### ProBee-ZE20S User Guide

Firmware version PTv1.X

### Copyright

Copyright 2011 Sena Technologies, Inc. All rights reserved.

Sena Technologies reserves the right to make changes and improvements to its product without providing notice.

### **Trademark**

ProBee™ is a trademark of Sena Technologies, Inc.

Windows® is a registered trademark of Microsoft Corporation.

Ethernet® is a registered trademark of XEROX Corporation.

### **Notice to Users**

When a system failure may cause serious consequences, protecting life and property against such consequences with a backup system or safety device is essential. The user agrees that protection against consequences resulting from system failure is the user's responsibility.

This device is not approved for life-support or medical systems.

Changes or modifications to this device not explicitly approved by Sena Technologies will void the user's authority to operate this device.

### **Technical Support**

Sena Technologies, Inc. 210 Yangjae-dong Seocho-gu Seoul 137-130, Korea

Tel: (+82-2) 573-5422 Fax: (+82-2) 573-7710 Email: <a href="mailto:support@sena.com">support@sena.com</a> Website: http://www.sena.com

Revision	Date	Name	Description
V1.0.0	2011-08-22	HR Zo	Initial Writing
V1.0.1	2011-09-29	HR Zo	Modification for ZE20S PTv1.4
			- Adding AT+RSSI Command
V1.0.2	2011-11.16	HR Zo	Modification of errors at 6.1 Development Kit
			Contents

# **Contents**

1 IN	ITRC	DDUCTION	11
1.1	Abo	out This Document	11
1.2	Ove	erview	11
2 G	ETTI	ING STARTED	13
2.1	Hai	rdware Installation	13
2.	1.1	Development Board Layout	13
2.	1.2	Antenna Installation	14
2.	1.3	Module Installation on the Development Board	14
2.	1.4	Serial/USB Cable Installation	
2.	1.5	Powering Development Board	
2.	1.6	USB Driver Installation	
2.2	Usi	ing Terminal Software for AT Commands	17
2.3	Usi	ing ProBee Manager for Configuration	18
2.3	3.1	Serial Port Open	18
2.3	3.2	Configuration	19
2.3	3.3	Firmware Update	21
3 <b>Z</b> I	GBE	E NETWORK CONFIGURATION	23
3.1	Set	tting up ZE20S as a Coordinator	23
3.	1.1	Node Type Selection for Coordinator	24
3.	1.2	Channel Mask Configuration for Coordinator	24
3.	1.3	PAN ID Configuration for Coordinator	25
3.	1.4	Permit Joining	25
3.2	Set	tting up ZE20S as a Router	26
3.2	2.1	Node Type Selection for Router	26
3.2	2.2	Channel Mask Configuration for Router	27
3.2	2.3	PAN ID Configuration for Router	27
3.2	2.4	Permit Joining	27
3.3	Set	tting up ZE20S as an End-Device	28
3.4	Set	tting up ZE20S as a Sleepy End-Device	29
3.5	Zig	Bee Security	30
3.8	5.1	Security Level	31
3.8	5.2	Link Key	31
3.8	5.3	Network Key	31
	5.4	Undate Kev	31

4 D	ATA	TRANSMISSION	32
4.1	Coi	mmand Mode	32
4.	1.1	Unicast	32
4.	1.2	Multicast	32
4.	1.3	Broadcast	33
4.	1.4	Sending Binary Data	34
4.	1.5	Display Incoming Message	34
4.2	Dat	a Mode	35
4.	2.1	Unicast Data Mode	35
4.	2.2	Multicast Data Mode	38
4.	2.3	Broadcast Data Mode	39
5 D	IGIT	AL AND ANALOG I/O	42
5.1	GP	IO (General Purpose Inputs and Outputs) Configuration	42
5.2	I/O	Sampling	43
5.	2.1	Queried Sampling	43
5.	2.2	Periodic Sampling	45
5.	2.3	Change Detection Sampling	46
5.	2.4	GPIO Remote Control	46
6 W	OR P	KING WITH DEVELOPMENT KIT	47
6.1	De	velopment Kit Contents	47
6.2	De	velopment Board Features	47
6.3	De	velopment Board Hardware Descriptions	48
6.	3.1	Power	48
6.	3.2	RS232 Port	48
6.	3.3	USB Port	49
6.	3.4	ZE20S GPIO Interface	49
6.	3.5	LEDs (CR12-19)	50
6.	3.6	Button Switches (SW10-17)	50
6.	3.7	Variable Resistors (VR1, VR2)	50
6.	3.8	Temperature Sensor	50
6.	3.9	Light Sensor	51
6.	3.10	Terminal Block	51
6.4	Coi	nfiguration Example #1: 1 Coordinator, 1 Router and 1 End-Device	51
6.	4.1	Coordinator Configuration	52
6.	4.2	Router Configuration	
6.	4.3	End-device Configuration	
6.	4.4	Monitoring the Sensors	
		nfiguration Example #2: 1 Coordinator and 2 End-Devices	

	6.5.1	Coordinator Configuration	54
	6.5.2	End-devices Configuration	54
	6.5.3	Turning on/off the LEDs	55
	6.6 Cc	onfiguration Example #3: Light Sensor and Temperature Sensor	55
	6.6.1	Coordinator Configuration	55
	6.6.2	Router Configuration	56
	6.6.3	Applying	57
	6.6.4	Queried Sampling	58
	6.6.5	Periodic Sampling – Destination Node	59
	6.6.6	Periodic Sampling – Sink Node	60
	6.6.7	Data Conversion	61
7	AT C	DMMAND REFERENCE	63
		ommand Line Format	
		andard AT Commands	
	7.2.1	AT	
	7.2.2	ATB	
	7.2.3	ATD	
	7.2.4	ATE	
	7.2.5	ATM	
	7.2.6	ATO	
	7.2.7	ATR	
	7.2.8	ATS	
	7.2.9	ATZ	
	7.2.10	AT&F	
	7.2.11	+++	
		ode Specific Information	
	7.3.1	AT+LONGADDR or AT+LA	
	7.3.2	AT+SHORTADDR or AT+SA	
	7.3.3	AT+ADDRDISCOVERY or AT+AD	
	7.3.4	AT+OPCH or AT+OC	
	7.3.5	AT+OPPANID or AT+OI	
	7.3.6	AT+OPEPID or AT+OE	
	7.3.7	AT+VERSION or AT+VR	
	7.3.8	AT+PRODUCTNAME or AT+PN	
	7.4 Ne	etwork Specific Parameters	
	7.4.1	AT+CHMASK or AT+CM	66
	7.4.2	AT+PANID or AT+PI	67
	<i>7.4.</i> 3	AT+EPID or AT+EI	67
	7.4.4	AT+GROUPID or AT+GI	67

7.4.5	AT+POWER or AT+PW	67
7.4.6	AT+STACK or AT+ZS	68
7.4.7	AT+NODENAME or AT+NN	68
7.5 Net	work Formation and Join	68
7.5.1	AT+ASCAN or AT+AS	68
7.5.2	AT+ESCAN or AT+ES	68
7.5.3	AT+DSCAN or AT+DS	69
7.5.4	AT+RSSI or AT+RS	69
7.5.5	AT+NODETYPE or AT+NT	69
7.5.6	AT+PERMIT or AT+PJ	70
7.5.7	AT+LEAVE or AT+LV	70
7.6 End	d-device	70
7.6.1	AT+SLEEP or AT+SM	70
7.6.2	AT+PARENTLA or AT+PL	70
7.6.3	AT+PARENTSA or AT+PS	70
7.6.4	AT+CHILDTABLE or AT+CT	70
7.7 Dat	a Transmission and Reception	71
7.7.1	AT+DESTLA or AT+DL	71
7.7.2	AT+DESTGROUPID or AT+DG	71
7.7.3	AT+SINKINFO or AT+SI	71
7.7.4	AT+MAXPAYLOAD or AT+MP	71
7.7.5	AT+TRASNSMITMODE or AT+TM	71
7.7.6	AT+UNICAST or AT+UC	72
7.7.7	AT+MULTICAST or AT+MC	72
7.7.8	AT+BROADCAST or AT+BC	72
7.7.9	AT+REMOTE or AT+RC	72
7.8 Sec	curity	72
7.8.1	AT+SECURITY or AT+SE	72
7.8.2	AT+LINKKEY or AT+LK	72
7.8.3	AT+NWKKEY or AT+NK	73
7.8.4	AT+UPDATEKEY or AT+UK	73
7.9 UA	RT	_
7.9.1	AT+BAUDRATE or AT+UB	73
7.9.2	AT+DATABIT or AT+UD	73
7.9.3	AT+PARITY or AT+UP	74
7.9.4	AT+STOPBIT or AT+US	74
7.9.5	AT+FLOWCTRL or AT+UF	74
7.10 GP	IO	74
7.10.1	AT+GPIO or AT+IO	74
7.10.2	AT+DIO	75

	7.10.3	AT+AI	75
	7.10.4	AT+ SOURCELA or AT+SL	75
-	7.11 Firr	mware Upload and Help	75
	7.11.1	AT+BOOTLOAD or AT+BL	75
	7.11.2	AT+HELP or AT+HP	76
8	AT CC	DMMAND EXAMPLES	77
8	3.1 Net	twork configuration	77
	8.1.1	Coordinator	77
	8.1.2	Router	77
	8.1.3	End-device	77
	8.1.4	Sleepy End-device	77
	8.1.5	Specifying Network	77
8	3.2 Dat	ta Transmission	78
	8.2.1	Command Mode	78
	8.2.2	Data Mode	79
8	3.3 Sec	curity	79
8	8.4 UA	RT Settings	80
8	8.5 GP	10	80
8	3.6 Firr	mware Upload	
	8.6.1	Local Node	
	8.6.2	Remote Node	81
9	S-REG	SISTERS	82
Ç	9.1 Dis	play Options	82
	9.1.1	S11	82
	9.1.2	S12	83
	9.1.3	S13	83
	9.1.4	S14	83
Ś	9.2 Net	twork Settings	83
	9.2.1	S21	83
	9.2.2	S22	84
	9.2.3	S23	84
Ç	9.3 Dat	ta Transmissions	84
	9.3.1	S31	84
	9.3.2	S32	84
	9.3.3	S33	85
	9.3.4	S34	85
	9.3.5	S35	85
	9.3.6	S36	86

9.3		
0.0	3.7 S37	86
9.3	3.8 S38	86
9.3	3.9 S39	86
9.4		
9.4	4.1 S41	87
9.4		
9.4		
9.4		
9.4		
9.5		
9.5		
9.5		
9.5		
9.5		
9.5		
9.5		
9.6		
9.6		
9.6	6.2 S62	90
10 F	PIN ASSIGNMENTS	91
	CONNECTIONS	93
<b>11 (</b> 11.1		93
<b>11 (</b> 11.1 11.2	Serial Port Pin Outs	93
11 ( 11.1 11.2 11.	Serial Port Pin Outs	93 94
11 ( 11.1 11.2 11. 11.	Serial Port Pin Outs  Serial Wiring Diagram	
11 ( 11.1 11.2 11. 11.	Serial Port Pin Outs Serial Wiring Diagram .2.1 To Host with DTE Interface .2.2 To Host with DCE Interface	93 94 94 95
11 ( 11.1 11.2 11. 11. 12 N	Serial Port Pin Outs Serial Wiring Diagram  .2.1 To Host with DTE Interface .2.2 To Host with DCE Interface  MECHANICAL DRAWINGS  WARRANTY	93 94 94 95 <b>95</b>
11 ( 11.1 11.2 11. 11.	Serial Port Pin Outs Serial Wiring Diagram  .2.1 To Host with DTE Interface .2.2 To Host with DCE Interface  MECHANICAL DRAWINGS  WARRANTY  GENERAL WARRANTY POLICY	93 94 94 95 97
11 ( 11.1 11.2 11. 11. 12 [ 13 ]	Serial Port Pin Outs Serial Wiring Diagram  .2.1 To Host with DTE Interface .2.2 To Host with DCE Interface  MECHANICAL DRAWINGS  WARRANTY  GENERAL WARRANTY POLICY  LIMITATION OF LIABILITY	93 94 94 95 95 97
11.1 11.2 11. 11. 12. 13. 13.1 13.2 13.3	Serial Port Pin Outs Serial Wiring Diagram  .2.1 To Host with DTE Interface .2.2 To Host with DCE Interface  MECHANICAL DRAWINGS  WARRANTY  GENERAL WARRANTY POLICY  LIMITATION OF LIABILITY	93 94 94 95 95 97 97
11.1 11.2 11. 11. 12 II 13.1 13.1 13.2 13.3 13.4	Serial Port Pin Outs Serial Wiring Diagram  2.1 To Host with DTE Interface  2.2 To Host with DCE Interface  MECHANICAL DRAWINGS  WARRANTY  GENERAL WARRANTY POLICY  LIMITATION OF LIABILITY  HARDWARE PRODUCT WARRANTY DETAILS	93 94 94 95 95 97 97 98
11.1 11.2 11. 11. 12 N 13.1 13.2 13.3 13.4 13.5	Serial Port Pin Outs Serial Wiring Diagram  .2.1 To Host with DTE Interface .2.2 To Host with DCE Interface.  MECHANICAL DRAWINGS.  WARRANTY  GENERAL WARRANTY POLICY  LIMITATION OF LIABILITY  HARDWARE PRODUCT WARRANTY DETAILS.  SOFTWARE PRODUCT WARRANTY DETAILS.	93 94 94 95 95 97 97 97 98
11 ( 11.1 11.2 11. 12 N 13 N 13.1 13.2 13.3 13.4 13.5	Serial Port Pin Outs Serial Wiring Diagram  2.1 To Host with DTE Interface 2.2 To Host with DCE Interface  MECHANICAL DRAWINGS  WARRANTY  GENERAL WARRANTY POLICY LIMITATION OF LIABILITY HARDWARE PRODUCT WARRANTY DETAILS SOFTWARE PRODUCT WARRANTY DETAILS THIRD-PARTY SOFTWARE PRODUCT WARRANTY DETAILS  REGULATORY INFORMATION	93 94 94 95 95 97 97 98 98
11.1 11.2 11. 11. 12. 13.1 13.2 13.3 13.4 13.5 14.1	Serial Port Pin Outs Serial Wiring Diagram  2.1 To Host with DTE Interface  2.2 To Host with DCE Interface  MECHANICAL DRAWINGS  WARRANTY  GENERAL WARRANTY POLICY LIMITATION OF LIABILITY  HARDWARE PRODUCT WARRANTY DETAILS  SOFTWARE PRODUCT WARRANTY DETAILS  THIRD-PARTY SOFTWARE PRODUCT WARRANTY DETAILS  REGULATORY INFORMATION  FCC	93 94 94 95 95 97 97 98 98 98
11 ( 11.1 11.2 11. 12	Serial Port Pin Outs Serial Wiring Diagram  2.1 To Host with DTE Interface  2.2 To Host with DCE Interface  MECHANICAL DRAWINGS  WARRANTY  GENERAL WARRANTY POLICY LIMITATION OF LIABILITY  HARDWARE PRODUCT WARRANTY DETAILS  SOFTWARE PRODUCT WARRANTY DETAILS  THIRD-PARTY SOFTWARE PRODUCT WARRANTY DETAILS  REGULATORY INFORMATION  FCC  CE	93 94 94 94 95 95 97 97 98 98
11. ( 11.1 11.2 11. 12. I 13. I 13.1 13.2 13.3 13.4 13.5 14. I 14.1 14.2 14.3	Serial Port Pin Outs Serial Wiring Diagram  2.1 To Host with DTE Interface  2.2 To Host with DCE Interface  MECHANICAL DRAWINGS  WARRANTY  GENERAL WARRANTY POLICY LIMITATION OF LIABILITY  HARDWARE PRODUCT WARRANTY DETAILS  SOFTWARE PRODUCT WARRANTY DETAILS  THIRD-PARTY SOFTWARE PRODUCT WARRANTY DETAILS  REGULATORY INFORMATION  FCC	93 94 94 95 95 97 97 98 98 98 98

ProBee-ZE20S	User	Guide	Rev 1	0.3	2

15	RF INFORMATION	10	)1
. •			•

### 1 Introduction

#### 1.1 **About This Document**

This document provides an introduction on configuration and operation of the ProBee-ZE20S ZigBee OEM module. This document assumes the user is using the ZE20S starter kit for evaluation hence the pictures and configuration examples shown in this document are all based on the ZE20S starter kit.

This document does not provide full detail of the hardware specifications. Please refer to the ProBee-ZE20S data sheet for further references on the hardware design.

#### 1.2 Overview

The ProBee-ZE20S is an all-in-one ZigBee OEM module with integrated ZigBee core and radio/antenna circuits together with high level software library. Using the ZE20S, OEM manufacturers can easily and cost-effectively integrate ZigBee functionality into target products in timely manner.

The ZE20S OEM module is designed to meet specific requirements of low cost and low power wireless applications such as home automation or smart energy by adopting the ZigBee technology. The ZE20S is based on the Ember EM357 ZigBee core and fully certified under the latest ZigBee Pro standard for the maximum compatibility.

Despite of its low cost and low power consumptions, the ZE20S provides high performance and robust data transfer capability for wide range of applications. The ZE20S can transfer data at up to 250 kbps and reach up to 1.0 km (0.62 miles) outdoor line-of-sight.

### **Key Features**

- Integrated 2.4GHz, IEEE 802.15.4-2003 compliant transceiver
- ZigBee Pro Certified
- ZigBee core: Ember EM357
- Transmit Power: +8dBm (Boost mode)
- Receiver Sensitivity: -102dBm @1% BER (Boost mode)
- TX Current: 45mA @3.3V (max.)
- RX Current: 31mA @3.3V (max.)
- Sleep Current: ≤1uA
- Working Distance: 1.0 km (0.62 miles) @ 3.3V, +5dBi Dipole Antenna
- Various Antenna/Connector Options: Dipole 1/3/5dBi, U.FL, RPSMA, Chip
- UART Signals Support: UART\_TXD/RXD, RTS/CTS, DTR/DSR
- 6 Analog Inputs
- 17 Digital Inputs/Outputs
- RoHS Compliant

## **Applications**

- Advanced Metering Infrastructure
- Home Area Networks (HAN)
- Neighborhood Area Networks (NAN)
- Home Automation
- Advanced lighting, entertainment and climate control systems
- Service-based monitoring, security and awareness systems
- **Commercial Building Automation**
- Climate & lighting control systems
- Industrial and Domestic Applications

### 2 **Getting Started**

Creating a ZigBee network using the ZE20S modules consists of the following steps:

- Install the ZE20S module on the development board
- Create a ZigBee network by configuring a ZE20S module as the coordinator
- Configure ZE20S modules as routers. This step is optional since the coordinator works as a router too.
- Configure ZE20S modules as end-devices
- Transmit data between ZE20S devices

This chapter describes how to install the ZE20S modules on to the development boards and how to use terminal software programs to access the ZE20S modules using AT commands for configurations and operations. The rest of the steps including ZigBee network creation, coordinator/router/end-device configurations and data transmissions are described in the following chapters. The more detailed information on the starter kit and the configuration examples are also provided in the later chapter.

#### 2.1 Hardware Installation

#### 2.1.1 **Development Board Layout**

Figure 2-1 shows the layout of the development board. The development board provides the interface between the ZE20S and the external serial port or USB port together with input/output terminals for convenient tests.

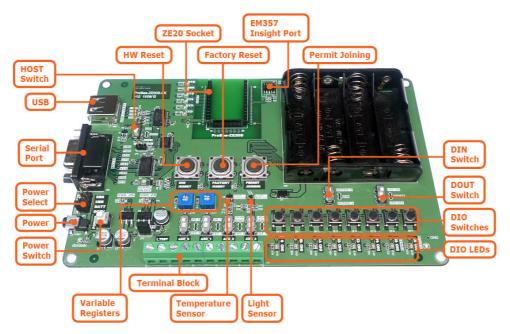


Figure 2-1 Development Board Layout

#### 2.1.2 **Antenna Installation**

The ZE20S starter kit includes the several antennas for evaluation purposes. You can try different antennas for testing purpose and select the appropriate antenna for the actual applications. Figure 2-2 shows how to install the RP-SMA dipole antenna to the ZE20S module.



Figure 2-2 RP-SMA Dipole Antenna Installation

### Module Installation on the Development Board

Once the antenna is installed on the ZE20S module, the ZE20S module can be installed on the development board.

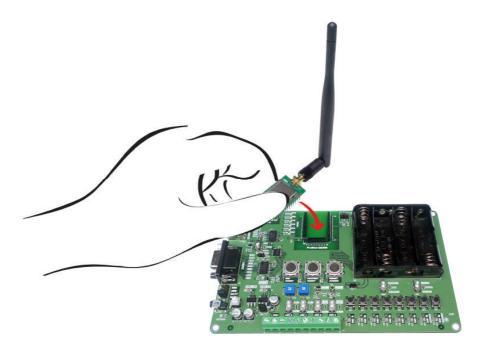


Figure 2-3 ZE20S Installation on the Development Board

### Serial/USB Cable Installation

After the ZE20S is securely installed on the development board, please connect the included serial cable between the development board and your computer so AT commands can be sent from the computer to the ZE20S module. The serial port of the development board is DB9 female as a DTE terminal, and the serial cable included is a cross-over cable for DTE-DTE connection. To use the serial port, the HOST (SW2) switch should be set to UART.

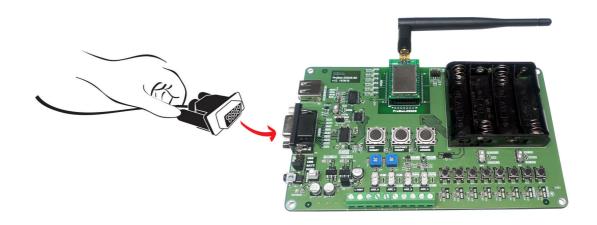


Figure 2-4 Serial Cable Installation

In case the serial port is not available for the computer, you can use the USB port of the development board instead. In this case, the internal USB-RS232 converter of the development board will convert the USB signal to the RS232 signal and vice versa. To use the USB port, the HOST (SW2) switch should be set to USB and the software driver for the USB in the CD should be installed on the computer. For the USB driver installation, please refer to the section 2.1.6.

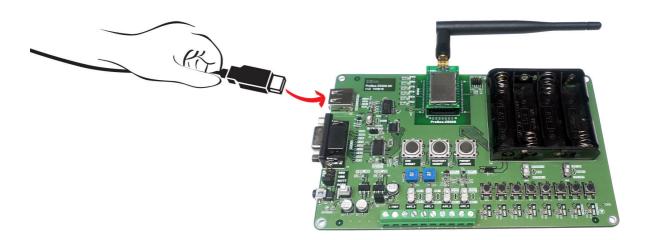


Figure 2-5 USB Cable Installation

### **Powering Development Board**

Once all the installations are completed, please plug in the power connector using the included DC power adapter. The RS\_PWR, USB\_PWR and BATT\_EN jumpers should be all OPEN to use the DC power adapter. Alternatively, the development board can be powered using batteries, or from the USB port or through the RS232 port pin 9. In these cases, the power source jumpers should be set accordingly. For details about the power source jumper settings, please refer to the section 6.3.1 Power.

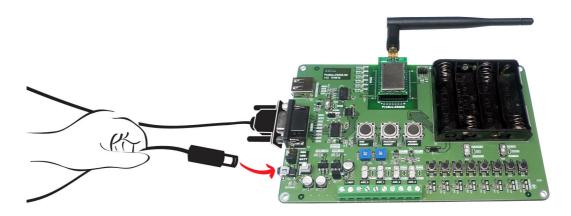


Figure 2-6 Plugging DC Power Adapter

#### 2.1.6 **USB Driver Installation**

In case the USB interface is used for the communication between the development board and the computer, the corresponding software driver needs to be installed on the computer. Windows XP and later versions already include the USB driver. When Windows asks for the location of the USB driver, you can select the option to "install the software automatically" as shown in Figure 2-7. You can also choose to install the driver from the CD included if the driver is not installed correctly for some reason.





Figure 2-7 USB Driver Installation

### 2.2 **Using Terminal Software for AT Commands**

Once the hardware installation is complete, the ZE20S unit is ready to communicate with the computer using the AT commands using a terminal emulation software. You can use any kind of terminal emulation software. This document assumes HyperTerminal is used. If you are using Windows Vista or 7, HyperTerminal is no longer included in the Windows so you need to download HyperTerminal from the Internet. For more details on HyperTerminal, please refer to Microsoft web page.

Once the HyperTerminal is installed, launch HyperTerminal and select the serial port that is connected to the ZE20S development board and enter the serial settings to use. The default serial settings of the ZE20S are 9600 bps, 8 data bit, none parity, 1 stop bit, hardware flow control.



Figure 2-8 HyperTerminal Serial Settings

To display the AT commands that are being typed, you need to enable the local echo option on the HyperTerminal. To enable this option, Go to File->Properties->Settings->ASCII setup and select the "Echo typed characters locally" option. To verify the connection, type AT and press the Enter key. If the AT command is accepted by the ZE20S, OK string will be displayed on the screen.

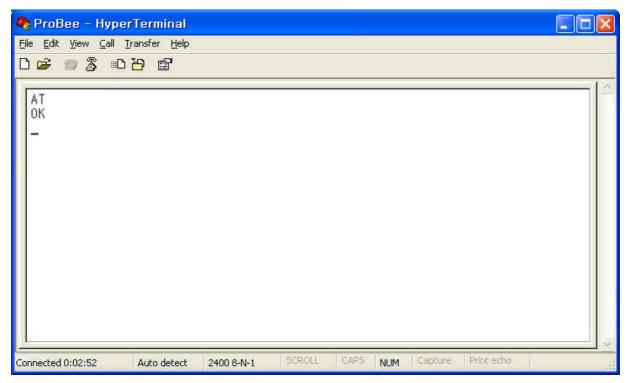


Figure 2-9 Testing AT Command on HyperTerminal

### 2.3 **Using ProBee Manager for Configuration**

It is possible to set or get the configurations of the ZE20S using ProBee Manager. This PC utility helps that a user can configure several setting values of local node and remote node easily without a terminal program. It is possible to export current configuration and import it to other nodes. It is also possible to restore to factory default configuration.

It provides users with functions to upgrade firmware of not only local node but also remote node.

#### 2.3.1 **Serial Port Open**



Figure 2-10 ProBee Manager Serial Port Open

To connect to local node through serial port, please follow the steps as below:

- Set 'Serial Port' properties corresponding to the UART configuration of local node.
- Click 'Open' button.

ProBee manager displays the main window like Figure 2-11 after connecting to local node.

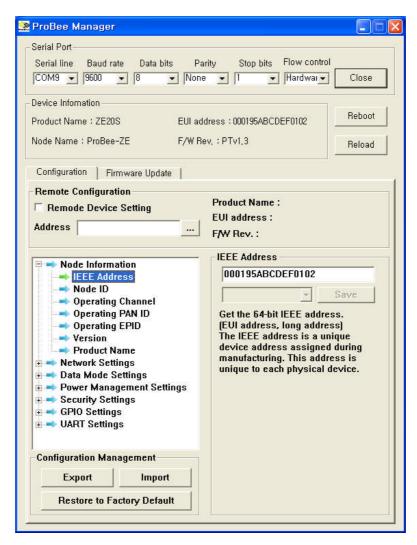


Figure 2-11 ProBee Manager Main Window

Clicking 'Reboot' button reboots the local node. Users can reload and refresh the recent configuration of the local node at ProBee manager by clicking 'Reload' button. 'Configuration' tab and 'Firmware Update' tab can help move to the 'Configuration' screen and the 'Firmware Upgrade' screen.

### Configuration

The Configuration Pane appears when the 'Configuration' tab is selected.

To change configuration, users need to find and modify the property and then apply changes. The properties are categorized according to the function. Selecting a category unfolds or folds the property list. The name, the current value and the description of the property are shown at the right of the configuration pane by selecting a property in the property list. It is possible to edit and save the current value of editable property. Whenever property is modified, it is necessary to save the change by clicking the 'Save' button

in order not lose it moving to other properties. To apply changes, please reboot the device by clicking 'Reboot' button. The 'Save' button is disabled for read-only property.



Figure 2-12 ProBee Manager Configuration Pane

In Figure 2-12, the 'Node Information' category is selected and the 'IEEE Address' property is selected, so Its description is displayed. The 'Save' button is disabled because the 'IEEE Address' property is readonly.

The configurations of the remote nodes joining the network where the local node belongs can be modified, too. Because a sleepy end-device often enters sleep mode, to remote configuration from a sleepy enddevice may not work.

To connect to local node through serial port, please follow the steps as below:

- Click the '...' button at 'Remote Configuration' section.
- Scan the remote nodes joining the network and select the remote node to configure, that results in displaying the remote node in the 'Address' edit box.
- Check the 'Remote Device Setting' check box and the caption of the 'Restore to Factory Default' button at the 'Configuration Management' section becomes 'Reboot' that makes the remote node reboot and configuration of the selected node is displayed.
- Select and modify the property.
- Click the 'Save' button.

Click the 'Reboot' button whose caption used to be 'Restore to Factory Default' to apply changes.

To export the configuration, please follow the steps as below:

- Click the 'Export' button at the 'Configuration Management' section and the 'Save As' dialog pops up.
- Select the path and enter the file name to store the configuration at.
- Click the 'Save' button' and the configuration is exported to the designated file.

Exported file can be used at other devices by importing them. The configuration of remote node can be exported and imported by checking the 'Remote Device Setting' check box.

Users can reset to factory default by clicking the 'Restore to Factory Default' at the 'Configuration Management' section.

#### 2.3.3 **Firmware Update**

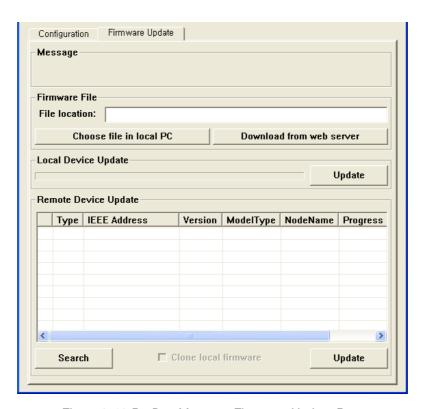


Figure 2-13 ProBee Manager Firmware Update Pane

The Firmware Update Pane appears when the 'Firmware Update' tab is selected. The 'Message' section displays informative message about the progress of updating firmware.

To update firmware at local node, please follow the steps as below:

- Select a firmware file to update at the 'Firmware Update' section. The 'Choose file in local PC' button pops up the dialog where users can select the firmware file at local PC and the 'Download from web server' button helps users download the firmware from web server.
- Click the 'Update' button at the 'Device Update' section to update the local node. The progress rate is expressed at the 'Local Device Update' section and informative messages are shown at 'Message' section.

ProBee Manager also supports to update the firmware of remote nodes which join the network where local node is. Because a sleepy end-device often enters sleep mode, to update remote node from a sleepy end-device may not work.

To update firmware at remote node, please follow the steps as below:

- Select a firmware file.
- Click the 'Search' button, that scans the remote nodes joining the network where local node belongs.
- Select the remote nodes to update in the remote nodes list.
- Click the 'Update' button at the 'Remote Device Update' section.

### 3 **ZigBee Network Configuration**

A ZigBee Network consists of a coordinator, routers and end-devices. A minimal ZigBee network consists of one coordinator and multiple end-devices which directly connect to the coordinator. For larger ZigBee networks, routers are required to provide redundant routings to form mesh networks.

- ZigBee Coordinator: The coordinator forms the root of the network tree and might bridge to other networks. There is exactly one ZigBee coordinator in each network since the coordinator starts the ZigBee network itself. It also stores information about the network, including acting as the Trust Center & repository for security keys.
- ZigBee Router: The routers are able to route messages between other devices. Since the coordinator provides the routing functionality too, the routers are optional to form a ZigBee network.
- ZigBee End-Device: The end-device contains just enough functionality to talk to the parent node which is either the coordinator or a router. It cannot relay data from other devices.
- ZigBee Sleepy End-Device: The sleepy end-device is the same with normal end-device except it can stay in the sleep mode much longer. This relationship allows the end-device to sleep significant amount of the time and achieve the long battery life.

The ZE20S can be configured to work either as a coordinator, a router, an end-device or a sleepy enddevice. Once the operation mode of the ZE20S is selected, corresponding parameters need to be set up appropriately. This chapter explains how to configure the ZE20S operation mode and other parameters related to the ZigBee network itself.

Node Type	Recommendation when to use ZE20S
Coordinator	It should be selected when it is first time to establish the network.
Router	It is recommended when there is a network already and it needs to be expanded. A
	router is suitable for fast and stable data transmissions and receptions.
End-Device	It is recommended when it doesn't need to expand the network anymore and there
	are enough nodes as parents. An end-device consumes less power than a router.
Sleepy End-Device	It is recommended when the data transmissions occur rarely and in very small
	quantities. A sleepy end-device can lose data if sleep duration is too long, but it is
	possible to consume extremely low power as low as 2uA.

Table 3-1 ZigBee Node Types

#### 3.1 Setting up ZE20S as a Coordinator

A coordinator relays messages and can act as a parent to other nodes. Every personal area network (PAN) must be started by a node acting as the coordinator. In general, this device is always powered on. To set up the ZE20S to work as the coordinator, please follow the steps as below

- Configure the ZE20S node type as the coordinator
- Optionally, select the channel mask. Otherwise, the ZE20S will use the default channel mask.
- Optionally, set up the PAN ID and/or the extended PAN ID. Otherwise, the ZE20S will generate the PAN ID and/or the extended PAN ID automatically.
- Permit joining when other router or end-device tries to join the ZigBee network.

### **Node Type Selection for Coordinator**

The ZE20S module can be configured as a ZigBee coordinator by the AT command as below:

```
AT+NODETYPE=n or AT+NT=n
```

```
, where n is 0 = none, 1 = coordinator, 2 = router, 3 = end-device, 4 = sleepy end-device
```

After the operation mode is selected, ATZ command should be performed to reset the unit to have the change applied.

### Example)

```
AT+NODETYPE=1<CR>
                        # Set node type as the coordinator
OK<CR>
                        # Response
ATZ<CR>
                        # Apply the change
OK<CR>
                        # Response
```

### **Channel Mask Configuration for Coordinator**

When the ZigBee coordinator starts, it scans predefined frequency channels to find the best frequency channel to use without causing interference with other wireless devices. The user is able to specify the channels to use with the AT command as below:

```
AT+CHMASK=n or AT+CM=n
```

```
, where n = channel mask to use. Default = 0x07FFF800
```

This value has a 32-bit hexadecimal unsigned integer. Each bit represents whether a channel will be used or not. For example, to use a channel between 12 and 15, the 12, 13, 14 and 15 bits of the channel mask should be 1 and all other bits should be 0. The default setting is 0x7FFF800 which means that all the channels from 11 to 26 can be used. The ZE20S supports only the channels between 11 and 26, so 0~10 bits and 27~31 bits should be 0. Table 3-2 shows the bit mask for each channel.

Channel 11 12 13 14 15 16 17 18 Bit mask 00000800 00001000 00002000 00004000 0008000 00010000 00020000 00040000 23 Channel 19 20 21 22 24 25 26 Bit mask 00080000 00100000 00200000 00400000 00800000 01000000 02000000 04000000

Table 3-2 Channel Bitmask

#### 3.1.3 **PAN ID Configuration for Coordinator**

Every ZigBee network should be assigned a PAN ID to identify the network. If the PAN ID is 0000, the ZE20S will generate a random 16-bit PAN ID to start the ZigBee network. Otherwise, the user can enter the PAN ID using the AT command as below:

AT+PANID=xxxx or AT+PI=xxxx

, where xxxx is PAN ID to use. For example, 12AB. Default setting is 0000

When choosing a PAN ID, the user needs to make sure that there is no ZigBee network using the same PAN ID. If the PAN ID is already used by another ZigBee network, the PAN ID is unavailable and the user should choose a new PAN ID. In order to avoid this, PAN ID auto-generation is strongly recommended.

The user can also assign the 64-bit extended PAN ID to the ZE20S using the AT command below. If the extended PAN ID is 00000000000000000, the ZE20S uses its IEEE address as the extended PAN ID. The extended PAN ID cannot be shared with other ZigBee networks, either.

AT+EPID=xxx...xxx or AT+EI= xxx...xxx

, where xxx···xxx is EPID to use. For example, 0123456789ABCDEF. Default setting is 000···000.

#### 3.1.4 **Permit Joining**

When a router or an end-device tries to join the ZigBee network, there should be at least one coordinator or router which is permitting joining. If there is no router in the ZigBee network yet, the coordinator should permit joining. The ZE20S provides three ways to permit joining are as follows:

- Permanently permitting by configuration
- Transiently permitting by AT command
- Transiently permitting by digital input signal

If joining is permanently permitted, any device can join anytime. Since this will allow even an unidentified device to join the network anytime, this mode should be selected with extra caution. The AT command to permit joining permanently is as follows:

AT+PERMIT=255 or AT+PJ=255

The user can permit joining for a moment at need. The AT command to permit joining is

AT+PERMIT=n or AT+PJ=n

, where n is the duration to permit in seconds ranging 1~254 seconds.

The user can also configure the ZE20S to permit joining when the digital input GPIO0 is active. The AT command to enable this functionality is as follows:

*AT+GPIO0=5* or *AT+IO0=5* 

When the ZE20S detects falling edge of the GPIO0, the ZE20S permits joining for the duration that is configured in S-register 22 (S22). The AT command to change the duration is as follows:

ATS22=n

, where n is the duration to permit in seconds ranging 1~254 seconds. Default is 255.

S22 value determines the time that the device will allow other devices to join to it. If set to 255, the device will always permit other nodes joining. If the user reboots the coordinator (or a router), the device allows other nodes to join the network for the period defined by S-register 22.

Note: When a device that has joined a network reboots, the device is able to join the network regardless of permitting. But, after the device has joined other network, rejoining the previous network should be permitted by the coordinator or a router.

#### 3.2 Setting up ZE20S as a Router

A router is a full-function routing device that relays messages and can act as a parent to other nodes. These devices must be always powered on.

To configure the ZE20S as a ZigBee router, please follow the steps below.

- Configure the ZE20S node type as a router.
- Optionally, select the channel mask. Otherwise, the ZE20S will use the default channel mask.
- Optionally, set up the PAN ID and/or the extended PAN ID. Otherwise, the ZE20S will scan and join the ZigBee network found automatically.
- Permit joining when other router or end-device tries to join the ZigBee network.

### 3.2.1 Node Type Selection for Router

The ZE20S module can be configured as a ZigBee router by the AT command as below:

AT+NODETYPE=n or AT+NT=n

, where n is 0 = none, 1 = coordinator, 2 = router, 3 = end-device, 4 = sleepy end-device

After the operation mode is selected, ATZ command should be performed to reset the unit to have the change applied.

### Example)

AT+NODETYPE=2<CR> # Select router mode

OK<CR> # Response

ATZ<CR> # Apply the change

OK<CR> # Response

#### 3.2.2 **Channel Mask Configuration for Router**

When the ZE20S as a ZigBee router or a ZigBee end-device tries to join, it scans all the channels configured by channel mask to find the ZigBee network to join. The channel mask of router or end-device should include the channel on which the coordinator is operating. On the assumption that the coordinator of the network to join is operating on channel 12, the router or end-device trying to join should have a channel mask of which 12<sup>th</sup> bit is 1.

### **PAN ID Configuration for Router**

The PAN ID of a ZigBee router or a ZigBee end-device should be the same with the PAN ID of the ZigBee coordinator. If the coordinator is using a randomly generated PAN ID, the user can get the operating PAN ID by running the AT command below on the coordinator:

### AT+OPPANID or AT+OI

If the PAN ID of a ZigBee router or a ZigBee end-device is 0000, the PAN ID is ignored. After checking the PAN ID, the ZE20S trying to join compares the extended PAN ID to make sure whether the network is the right network to join. If the extended PAN ID is the same with its configured extended PAN ID, it will try to join the network. Otherwise, it will try to find another network. The user can get the operating extended PAN ID by running the AT command below on the coordinator:

### AT+OPEPID or AT+OE

If the extended PAN ID of a ZigBee router or a ZigBee end-device is 00000000000000, the extended PAN ID is ignored

#### **Permit Joining** 3.2.4

The ZigBee router is configured and works the same way with the coordinator to permit joining of other nodes. Please refer to the section 3.1.4 Permit Joining for the configuration.

### 3.3 Setting up ZE20S as an End-Device

An end-device is a leaf node which communicates only with its parent node and will not relay messages directly. To configure the ZE20S as a ZigBee end-device, please follow the steps below.

- Configure the ZE20S node type as an end-device
- Optionally, select the channel mask. Otherwise, the ZE20S will use the default channel mask.
- Optionally, set up the PAN ID and/or the extended PAN ID. Otherwise, the ZE20S will scan and join the ZigBee network found automatically.
- Configure the poll timeout and the poll period

Please refer to the section 3.2 Setting up ZE20S as a Router for the AT commands regarding the node type selection, the channel mask configuration and the PAN ID/Extended PAN ID configuration.

When an end-device joins the network, the power LED blinks periodically if GPIO15 is set to specific functionality. The end-device belongs to a parent node which is either the coordinator or a router, and the parent node registers the end-device to its internal child table for message relaying. This table is maintained as long as the end-device polls the parent node periodically within the poll timeout value of the parent node. If the end-device does not poll for the poll timeout value of the parent node, the parent node removes the end-device from its child table and does not relay the message any more. Hence, the poll period of the end-device should be equal or shorter than the poll timeout of the parent node to avoid accidental removal of the end-device from the parent node's child table.

The ZE20S poll interval can be configured by setting the S-registers using the AT commands as below.

ATS51=n, where n is poll timeout in seconds and the default is 60.

This value is for a parent node. If an end-device does not send a poll request to its parent coordinator or router within the poll timeout, the end-device is removed from the child table.

ATS56=n, where n is poll period in seconds and the default is 5.

End-device polls the parent node at poll period defined by S56 periodically. It is for the connection to the parent node and data transmission with other nodes in the network.

ATS55=n, where n is rejoin timeout and the default is 10.

When the connection to the parent node is broken for S55 in seconds, the child node tries to rejoin the current network.

Even though the end-device needs to poll the parent node continuously, it does not go into the sleep mode and it can send and receive messages any time unlike the sleepy end-device.

### 3.4 Setting up ZE20S as a Sleepy End-Device

A sleepy end-device can turn off radio to save power. To configure the ZE20S as a ZigBee sleepy enddevice, please follow the steps below.

- Configure the ZE20S node as a sleepy end-device.
- Optionally, select the channel mask. Otherwise, the ZE20S will use the default channel mask.
- Optionally, set up the PAN ID and/or the extended PAN ID. Otherwise, the ZE20S will scan and join the ZigBee network found automatically.
- Configure the settings for sleep interval.

Please refer to the section 3.2 Setting up ZE20S as a Router for the AT commands regarding the node type selection, the channel mask configuration and the PAN ID/Extended PAN ID configuration.

One of the unique features of the ZigBee device is its extreme low power consumption which is mainly achieved by its efficient sleep and wake-up mechanism. While ZigBee coordinator and routers are required to be in operation all the time, ZigBee sleepy end-devices can be configured to be in the sleep mode most of the time and only wake up at pre-configured time interval for data transmission before it goes into the sleep mode again. The ZE20S sleep interval can be configured by setting the S-registers using the AT commands as below.

ATS51=n, where n is poll timeout in seconds and the default is 60.

This value is for a parent node. If a sleepy end-device does not send a poll request to its parent coordinator or router within the poll timeout, the sleepy end-device is removed from the child table.

Unlike the non-sleepy end-device, sleepy end-device does not use S56 as the poll period. Instead, it uses S53 as the sleep duration which works similar to the poll period, except it goes to sleep mode.

ATS53=n, where n is sleep duration in quarter seconds and the default is 8.

The ZE20S sleeps for sleep duration and turns off radio.

ATS52=n, where n is poll period in milliseconds and the default is 100.

Sleepy end-device wakes up from the sleep mode if S53 timer expires or GPIO0 interrupt is generated or serial data is received. Once the sleepy end-device wakes up, it polls the parent node at poll period defined by S52 until it goes to sleep mode again. Since the sleepy end-device exchanges data with the parent node only by polling, S52 poll period is usually configured as around 100 ms.

ATS54=n, where n is standby timeout in seconds and the default is 5.

If there is no RF data or serial data for S54 seconds, the sleepy end-device goes to sleep mode again. If any serial or RF data is sent or received, the timer will reset and the sleepy end-device waits for another S54 seconds before it goes to sleep mode again.

ATS55=n, where n is rejoin timeout and the default is 10.

When the connection to the parent node is broken for S55 in seconds, the child node tries to rejoin the current network.

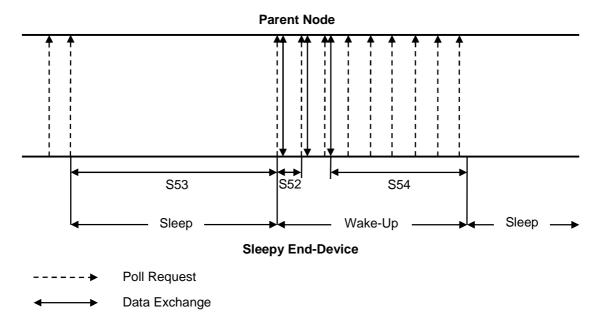


Figure 3-1 Sleep Interval and Wake-up Timing

The sleepy end-device can also wake up from the sleep mode by GPIO0 interrupt or incoming serial data. Once it wakes up, it also polls with the parent node at S52 interval and goes into sleep mode after S54 time elapses after the last data exchange.

Note: If the sleepy end-device wakes up by incoming serial data, the integrity of the first incoming byte is not guaranteed. It is strongly recommended to wake up the sleepy end-device by using GPIO0 first before sending the serial data or use higher level serial data protocol to check the data integrity.

### 3.5 **ZigBee Security**

Security is a major concern in the ZigBee architecture. Although ZigBee uses the basic security elements in IEEE 802.15.4 (e.g., AES encryption & CCM security modes), the ZE20S increases the security level with:

- 128 bit AES encryption algorithms
- Strong, NIST-approved security
- Defined Key Types (Link, Network)
- Defined Key setup and maintenance

- CCM (Unified/Simpler mode of operation)
- Trust Centers

#### 3.5.1 **Security Level**

In order to use security in the application, a user should set security level using the AT command below. Set 1 defines both Authentication and Encryption at the network layer. Set 0 defines no security. Disabling security in the application is not ZigBee compliant. All nodes in the network should have the same security level setup. The security level is configured using the AT command below.

AT+SECURITY=n or AT+SE=n, where n is encryption level. (0=disable, 1=enable)

#### 3.5.2 Link Key

The trust center (normally coordinator in network) requests link key before a device is trying to join network. If link key the device has is wrong, joining process will be denied. Hence, all nodes in the network should have the same link key setup before joining the network.

AT+LINKKEY=xxx···xxx or AT+LK= xxx···xxx, where xxx···xxx is 128-bit hexadecimal trust center link key. Default is FFF...FF.

#### 3.5.3 **Network Key**

It is the network-wide key used to secure transmissions at the Network Layer. The network key encrypts all transmissions at the Network Layer. The network key only needs to be set up for the coordinator.

AT+NWKKEY=xxx···xxx or AT+NK=xxx···xxx, where xxx···xxx is 128-bit hexadecimal network key. Default is FFF...FF.

#### 3.5.4 **Update Key**

A trust center can update the Network Key to help minimize the risk associated with a particular instance of the network key being compromised. Key updates are broadcast by the trust center throughout the network, encrypted using the current network key. Devices that hear the broadcast will not immediately use the key, but simply store it. Later, a key switch is broadcast by the trust center to tell all nodes to start using the new key. At a minimum, the trust center should allow adequate time for the broadcast of the new key to propagate throughout the network before switching.

AT+UPDATEKEY<CR> or AT+UK<CR>

### 4 **Data Transmission**

The ZE20S supports three different types of data transmissions: unicast, multicast and broadcast. Unicast is to transmit data to a specific ZigBee device. Multicast is to transmit data to a group of ZigBee devices that are assigned a specific group ID. Broadcast is to transmit data to all ZigBee devices (or specific type of ZigBee nodes if specified) in the network.

ZE20S has such operation modes as command mode and data mode. Data can be transmitted at each operation mode as below:

- Command mode: Because this mode is for entering commands to set and manage a ZE20S, as many data as allowed are transmitted at a time by using AT command.
- Data mode: Because this mode is for transmitting data, it is possible to send data consecutively. "+++" changes the operation mode from the data mode to command mode.

#### 4.1 **Command Mode**

#### 4.1.1 Unicast

Unicast transmissions are sent from a source device to a destination device. The destination device can be any ZigBee device in the ZigBee network. To specify the destination device, the ZigBee address of the destination device should be known.

There are two different ZigBee addresses assigned to each ZigBee device. The 64-bit address is a unique device address assigned during manufacturing. The 64-bit address is also called IEEE address or extended address. The 16-bit address is assigned to the device when it joins a ZigBee network. The ZE20S can send unicast messages based on either 16-bit address or 64-bit address. The AT command for the unicast transmissions is as below:

```
AT+UNICAST=<node id>,<MSG><CR> or AT+UC=<node id>,<MSG><CR>
, where <node_id> = 16-bit or 64-bit address, <MSG> = data to transmit
```

The maximum payload of the message is 90 bytes (or 72 bytes under security enabled). If the message length exceeds the maximum payload, the message cannot transmit and the error message will be presented. The AT command to get the maximum payload is as below:

AT+MAXPAYLOAD?<CR> or AT+MP?<CR>

#### 4.1.2 Multicast

Multicast transmissions are sent from a source device to destination devices with the specific group ID. The group ID is assigned to the devices using the AT+GROUPID command. The AT command for the multicast transmissions is as below.

AT+MULTICAST=<group\_id>,<MSG><CR> or AT+MC=<group\_id>,<MSG><CR> , where <group\_id> = group ID, <MSG> = data to transmit

The data transmission range can be set using the AT commands below. Please refer to the 9 S-Registers for more details.

ATS36=n, where n is the radius.

ATS37=n, where n is the number of hops through nonmembers.

Note: ZigBee compliance rules prevents flooding of the network by limiting the network to a maximum of 9 broadcasts over 8 seconds. Attempts to submit additional broadcasts beyond this should result in the transmission error. This is approximately one broadcast per second. It is, however, recommended to broadcast one packet over 2 seconds for safe transmission. Broadcast transmission failure also causes retransmission which is affected by transmission timeout(S33) and transmission retries(S32). Because frequent retransmissions may cause to break the broadcast limitation, it is recommended to set more than 1000 for transmission timeout(S33) and set as small as possible for transmission retries(S32).

Multicast data transmission is implemented on top of the network broadcast mechanism, so it is subject to the same rules.

#### 4.1.3 **Broadcast**

Broadcast transmissions are sent from a source device to all devices in the ZigBee network. The AT command for the broadcast transmissions is as below.

```
AT+BROADCAST=<MSG><CR> or AT+BC=<MSG><CR>
, where <MSG> = data to transmit
```

The user can also specify the transmission range by changing the S35 register value as below. Please refer to the 9 S-Registers for more details.

ATS35=n, where n is the broadcast range.

ATS36=n, where n is the radius.

Note: ZigBee compliance rules prevents flooding of the network by limiting the network to a maximum of 9 broadcasts over 8 seconds. Attempts to submit additional broadcasts beyond this should result in the transmission error. This is approximately one broadcast per second. It is, however, recommended to broadcast one packet over 2 seconds for safe transmission. Broadcast transmission failure also causes retransmission which is affected by transmission timeout(S33) and transmission retries(S32). Because frequent retransmissions may cause to break the broadcast limitation, it is recommended to set more than 1000 for transmission timeout(S33) and set as small as possible for transmission retries(S32).

Multicast data transmission is implemented on top of the network broadcast mechanism, so it is subject to

the same rules.

#### 4.1.4 **Sending Binary Data**

Because some characters like carriage return, line feed and back space collides with AT commands in command mode and back slash('\') is used for control character for binary encoding, they cannot be transmitted as they are. The characters out of range between 0x20(Space) and 0x7E('~') in hexadecimal are not expressed at the AT commands for transmitting data. In order to transmit these characters in command mode, these characters must be encoded in a command line. The examples of special characters encoding are shown in Table 4-1.

HEX	Abbreviation	Glyph	Encoded	Description
00	NULL	-	\00	Null character
0D	CR	-	\0D	Carriage return
0A	LF	-	\0A	Line feed
08	BS	-	\08	Backspace
09	HT	-	\09	Horizontal Tab
7F	DEL	-	\7F	Delete
5C	-	\	\5C	Control character for binary encoding

Table 4-1 Examples of Special Characters Encoding

For example, when sending abc<CR> with AT+BROADCAST command, the command should be as follows:

AT+BROADCAST=abc\0D<CR>

### **Display Incoming Message**

S11 register determines whether incoming message will be shown or not in the command mode. In the data mode, on the other hand, incoming data is always displayed. To change the S11 register, please use the AT command as below:

ATS11=<value><CR>

, where <value> = 0 to hide incoming message, 1 to show incoming message.

If user wants to display incoming message in command mode, S11 should be enabled. It is displayed by the form of +</EEE address>|<MSG><CR>.

When displaying incoming messages in command mode, some characters are encoded in the same way with sending binary data as in Table 4-1. For example, when receiving abc<CR> from 0001950000000001, the displaying message is as follows:

+0001950000000001| abc\0D<CR>

Note: In PTv1.2 or earlier version, only the characters mentioned at Table 4-1 are encode. In PTv1.3 or later version, back slash('\') and the characters out of range between 0x20(Space) and 0x7E('~') in hexadecimal are encoded.

#### 4.2 **Data Mode**

If the data is too long to send using the command mode, Data Mode can be used instead. Once the ZE20S enters a Data Mode session, the ZE20S can send data continuously to a specific node or current network until the data mode is escaped. The data is packetized and transmitted at every inter character timeout. This data link to the designated device is maintained until the escape command "+++" is entered. To return to the last data mode after the ZE20S is escaped by "+++", use the AT command as below.

ATO<CR>

#### 4.2.1 **Unicast Data Mode**

Unicast data mode can be used for continuous data transmission to a particular node. Unicast data mode can be entered using either ATD or AT+TRANSMITMODE=1 (or 4). ATD command is the command for entering the unicast data mode. AT+TRANSMITMODE=1 is used to set the data transmission mode to unicast to destination long address and AT+TRANSMITMODE=4 to unicast to sink node.

If ATD command is used, the device will enter the unicast data mode immediately and keep it until escaped using "+++" or reset by ATZ. If the device is reset, it will not enter the unicast data mode but command mode in this case.

On the other hand, if AT+TRANSMITMODE=1 (or 4) is used to enter the unicast data mode, the device enters the unicast data mode again whenever the device is reset. To disable the unicast data mode, escape the data mode first by using "+++" string and use AT+TRANSMITMODE=0 and reset the device to apply the setting permanently.

AT commands used for the unicast data mode are as below.

AT+DESTLA=<value> or AT+DL=<value>

, where <value> is 64-bit IEEE address of destination node for unicast data mode. Set the destination address which is used for ATD command or AT+ TRANSMITMODE=1.

### ATD<CR>

Set unicast data mode to the preconfigured destination IEEE address without reset.

### ATD<value><CR>

Set unicast data mode to <value> device and <value> can be either 16-bit node ID or 64-bit IEEE address of remote node.

### AT+TRANSMITMODE=1<CR> or AT+TM=1<CR>

Set the transmission mode to unicast to a destination IEEE address. The device should be reset to apply the transmission mode.

The 'unicast to sink node data mode' is a kind of unicast data mode where data are not transmitted to the designated destination device but to sink node. A device can be a sink node by setting S-register 61. The sink node multicasts its address to the other devices in the destination group in the network according to the value of S-register 61, which is called advertising. The other devices in the network store the address of the sink node. The devices in the 'unicast to sink node data mode' transmits data to the sink node.

The 'unicast to sink node data mode' is useful for a device to gather data from many devices because every device comes to know the destination device by setting the destination device as sink node instead of describing the destination device to every device. Every device also comes to know the new destination device by changing the sink node in the network.

AT commands used for the 'unicast to sink node data mode' are as below.

### ATS61=<value><CR>

, where <value> = 0 not sink node, <value> > 0 sink node to advertise its address to the devices in the destination group (AT+DESTGROUPID) every <value> second.

### AT+DESTGROUPID=<value> or AT+DG=<value>

, where <value> is 16-bit destination group ID to which sink node advertises its address. Set destination Group ID of the device.

### AT+SINKINFO?<CR> or AT+SI?<CR>

Get the long and short addresses of sink node. If there is no sink node in the network, the addresses will be "FFFFFFFFFFFF" and "FFFF".

### AT+TRANSMITMODE=4<CR> or AT+TM=4<CR>

Set the transmission mode to unicast to a sink node. The device should be reset to apply the mode.

### Example)

AT+DESTLA=00019500002FDC40<CR> # Set the destination IEEE address OK<CR> # Response ATD<CR> # Enter the unicast mode using destination IEEE address OK<CR> # Response

# Put the unicast message Send unicast msg

+++ # Leave data mode

OK<CR> # Response

ATD0000<CR> # Enter the unicast mode using 16-bit node ID

OK<CR> # Response

# Put the unicast message Send unicast msg

# Leave data mode +++

# Response OK<CR>

ATD00019500002FDC40<CR> # Enter the unicast mode using 64-bit IEEE address

OK<CR> # Response

Send unicast msg # Put the unicast message

# Leave data mode +++

OK<CR> # Response

AT+DESTLA=00019500002FDC40<CR> # Set the destination IEEE address

# Response

AT+TRANSMITMODE=1<CR> # Set transmission mode to destination IEEE address

OK<CR> # Response

ATZ<CR> # Apply to change

OK<CR> # Response

Send unicast msg # Put the unicast message

# Leave data mode +++

OK<CR> # Response

AT+TRANSMITMODE=4<CR> # Set transmission mode to sink node in the network

OK<CR> # Response

ATZ<CR> # Apply to change

OK<CR> # Response

Send unicast msg # Put the unicast message

+++ # Leave data mode

OK<CR> # Response

### 4.2.2 Multicast Data Mode

Multicast data mode can be used for continuous data transmission to a particular group of multiple devices. Every ZE20S belongs to a certain group by predetermined group ID when forming or joining the network.

Multicast data mode can be entered using either ATM or AT+TRANSMITMODE=2. If ATM command is used, the device will enter the multicast data mode immediately and keep it until escaped using "+++" or reset by ATZ. If the device is reset, it will not enter the multicast data mode but command mode in this case.

On the other hand, if AT+TRANSMITMODE=2 is used to enter the multicast data mode, the device enters the multicast data mode again whenever the device is reset. To disable the multicast data mode, escape the data mode first by using "+++" string and use AT+TRANSMITMODE=0 and reset the device to apply the setting permanently.

AT commands used for the multicast data mode are as below.

AT+GROUPID=<value> or AT+GI=<value>, where <value> is 16-bit group ID for multicast data mode. Set Group ID of the device. The device will receive the multicast data sent to this Group ID.

AT+DESTGROUPID=<value> or AT+DG=<value>, where <value> is 16-bit destination group ID for multicast data mode.

Set destination Group ID of the device.

### ATM<CR>

Set multicast data mode to preconfigured destination group ID without reset.

### ATM<value><CR>

Set multicast data mode to <value> group ID and <value> can be 16-bit ID.

### AT+TRANSMITMODE=2<CR> or AT+TM=2<CR>

Set the transmission mode to multicast mode. The device should be reset to apply the mode.

ATS36=n, where n is the radius.

ATS37=n, where n is the number of hops through nonmembers.

Set data relay and forwarding options. Please refer to the 9 S-Registers for more details.

Note: ZigBee compliance rules prevents flooding of the network by limiting the network to a maximum of 9 broadcasts over 8 seconds. Attempts to submit additional broadcasts beyond this should result in the transmission error. This is approximately one broadcast per second. It is, however, recommended to broadcast one packet over 2 seconds for safe transmission. Broadcast transmission failure also causes retransmission which is affected by transmission timeout(S33) and transmission retries(S32). Because frequent retransmissions may cause to break the broadcast limitation, it is recommended to set more than 1000 for transmission timeout(S33) and set as small as possible for transmission retries(S32).

Multicast data transmission is implemented on top of the network broadcast mechanism, so it is subject to the same rules.

### Example)

```
AT+DESTGROUPID=0001<CR>
                           # Set the destination group ID
OK<CR>
                       # Response
ATM<CR>
                       # Enter the multicast mode using destination group ID
OK<CR>
                        # Response
Send multicast msg
                       # Put the multicast message
+++
                        # Leave data mode
OK<CR>
                       # Response
```

```
ATM0001<CR>
                        # Enter the multicast mode using 16-bit group ID
OK<CR>
                        # Response
Send multicast msg
                        # Put the multicast message
                        # Leave data mode
OK<CR>
                        # Response
```

```
AT+DESTGROUPID=0001<CR>
                           # Set the destination group ID
OK<CR>
                           # Response
AT+TRANSMITMODE=2<CR>
                           # Set transmission mode to destination group ID
OK<CR>
                           # Response
ATZ<CR>
                           # Apply to change
OK<CR>
                           # Response
Send multicast msg
                           # Put the multicast message
+++
                           # Leave data mode
OK<CR>
                           # Response
```

### **Broadcast Data Mode**

Broadcast data mode can be used for continuous data transmission to all devices in the current network. The destination address or group ID of the remote nodes is not necessary for broadcast data mode. The transmit range is determined by the S-register 35.

Broadcast data mode can be entered using either ATB or AT+TRANSMITMODE=3. If ATB command is used, the device will enter the broadcast data mode immediately and keep it until escaped using "+++" or reset by ATZ. If the device is reset, it will not enter the broadcast data mode but command mode in this case.

On the other hand, if AT+TRANSMITMODE=3 is used to enter the broadcast data mode, the device enters the broadcast data mode again whenever the device is reset. To disable the broadcast data mode, escape the data mode first by using "+++" string and use AT+TRANSMITMODE=0 and reset the device to apply the setting permanently.

AT commands used for the broadcast data mode are as below.

### ATB<CR>

Set broadcast data mode.

### AT+TRANSMITMODE=3<CR> or AT+TM=3<CR>

Set the transmission mode to broadcast. It should be reset to apply the mode.

ATS35=n, where n is the broadcast range.

ATS36=n, where n is the radius.

Set data transmission range. Please refer to the chapter 9 S-Registers for more details.

Note: ZigBee compliance rules prevents flooding of the network by limiting the network to a maximum of 9 broadcasts over 8 seconds. Attempts to submit additional broadcasts beyond this should result in the transmission error. This is approximately one broadcast per second. It is, however, recommended to broadcast one packet over 2 seconds for safe transmission. Broadcast transmission failure also causes retransmission which is affected by transmission timeout(S33) and transmission retries(S32). Because frequent retransmissions may cause to break the broadcast limitation, it is recommended to set more than 1000 for transmission timeout(S33) and set as small as possible for transmission retries(S32).

Multicast data transmission is implemented on top of the network broadcast mechanism, so it is subject to the same rules.

### Example)

```
ATS35=2<CR>
                        # Set broadcast range to all nodes in the network
OK<CR>
                        # Response
                        # Enter the broadcast mode
ATB<CR>
OK<CR>
                        # Response
Send broadcast msq
                        # Put the broadcast message
                        # Leave data mode
+++
```

OK <cr></cr>	# Response
AT+TRANSMITMODE=3 <cr></cr>	# Set transmission mode to current network
OK <cr></cr>	# Response
ATZ <cr></cr>	# Apply to change
OK <cr></cr>	# Response
Send broadcast msg	# Put the broadcast message
+++	# Leave data mode

# Response

OK<CR>

### Digital and Analog I/O 5

#### 5.1 **GPIO (General Purpose Inputs and Outputs) Configuration**

The ZE20S module has total 18 I/O pins. Among these pins, I/O pin 2 is assigned to factory reset only and the user can use the rest 17 pins for general purpose inputs and outputs. The I/O pin assignments are shown in Table 5-1. As shown in Table 5-1, some pins provide special functions built into the firmware. Table 5-2 describes the special functions tied to the specific pins.

Pin Number **GPIO** Number **Special Functions** Al Enable Factory reset / Bootloader (SW\_0) Χ Χ 3 0 Permit joining / Wake-up (SW\_1) Χ 1 UART DTR 4 Χ 5 2 UART\_DSR 3 UART CTS Χ 6 UART\_RTS Χ 7 4 Χ 8 5 6 Χ 9 7 Χ 10 Χ 11 8 9 O (AI\_0) 32 31 10 O (AI\_1) 30 11 O (AI\_2) 29 12 O (AI\_3) 28 13 O (AI\_4) 27 14 O (AI\_5) 24 Power LED (LED 0) Χ 15 Χ 23 16 Status LED (**LED\_1**)

Table 5-1 Default I/O Pin Assignments

The AT command below can be used to change the GPIO settings.

AT+GPIO=<values><CR> or AT+GPIO<number>=<value><CR>

- , where <values> is a number between 0~5 as explained below:
  - Disabled (unmonitored digital input)
  - 1 Digital input, monitored
  - 2 Digital output, default low
  - 3 Digital output, default high
  - 4 Analog input, single ended (only valid for GPIO9~14)
  - Reserved for pin-specific alternate functionalities (See Table 5-2)

Table 5-2 Special GPIO Pins

Function	GPIO#	Туре	Description	
Factory_reset / Bootloader	-	DI	This input is dedicated for the factory reset button. If user wants to restore the ZE20S device settings to factory default, this input (rising edge, i.e. Low to High change) needs to be pressed for more than two seconds. It will be applied after the input released again. If this input is pressed while the ZE20S starts, the local node enters bootloader menu and it is possible to upload the firmware.	
Permit_joining / Wake-up	0	This input (rising edge, i.e. Low to High change) is used to permit joining or interrupt sleeping. This function is activated when GPIO0 is set to 5. The functions depend on the node type of the ZE20S. If the node is set to coordinator or router, this input works to permit other nodes joining for Permit joining timeout(S-register 22 value). If the node is set to sleepy end-device, it is used for wake-up signal when the node is sleeping.		
UART_CTS	1	DI	This input is used for UART CTS if GPIO1 is set to 5. It should be enabled when CTS flow control is used.	
UART_RTS	2	DO  This output is used for UART RTS if GPIO2 is set to 5. It should be enabled when RTS flow control is used.		
UART_DTR	3	DO	This output is used for UART DTR if GPIO3 is set to 5.	
UATR_DSR	4	DI	This input is used for UART DSR if GPIO4 is set to 5.	
Power LED	15	DO	If GPIO15 is set to 5, this output turns ON (High) when power supplied. If the node is set to an end-device, it will blink periodical Please refer to <b>9 S-Registers</b> for S14 regarding the management the LED status.	
Status LED	16	DO	If GPIO16 is set to 5, this output turns ON (High) when the device joins a network, blinks when joining is permitted, and turns OFF (Low when leaves the network. Please refer to <b>9</b> <i>S-Registers</i> for S1 regarding the management of the LED status.	

#### 5.2 I/O Sampling

The I/O status can be monitored and controlled using the AT commands. The I/O status of remote device can be monitored and controlled using remote AT commands, too. The ZE20S can also be configured to sample the I/O status and send to a remote device periodically.

#### 5.2.1 **Queried Sampling**

The I/O status can be monitored and controlled using the AT commands either locally or remotely. To read the digital I/O line values, the AT+DIO command can be used as below. Return value is a combination of 0 (Low) and 1 (High) if the pins are configured as digital I/O lines. If the pins are configured as analog inputs, the corresponding return values are shown as \*.

### AT+DIO?<CR> or AT+DIO<number>?<CR>

, where <number> is the specific IO number between ranges 0  $\sim$  16 to read

AT+DIO command can also be used to set the digital output lines.

### AT+DIO=<value><CR> or AT+DIO<number>=<value><CR>

, where <number> is the specific IO number between ranges 0 ~ 16 to read, and the <values> is a combination of 0 or 1, 0 = Low, 1 = High

The analog input values can be read using the AT+AI command. Return value is a combination of 16-bit hexadecimal integer between 0~2EE0(0~1200mV) or D120-FFFF(-1200~-1mV) which unit value corresponds to 0.1mv. To convert the hexadecimal value to the actual voltage, please use the formula below. If the pins are configured as digital I/Os, the corresponding return values are shown as \*.

### AT+AI?<CR> or AT+AI<number>?<CR>

, where <number> is the specific IO number between ranges 0 ~ 5 to read If the Value is between 0 ~ 2EE0, Voltage (mV) = Value \* 0.1 If the Value is between D120 ~ FFFF, Voltage (mV) = (Value - 65536) \* 0.1

### Example)

```
AT+DIO?<CR>
10001000111**0000
                        ← DIO 0, 4, 8, 9, 10 are ON. GPIO11, 12 are configured
as analog inputs
AT+DIO0=0<CR>
OK
AT+DIO?<CR>
00001000111**0000
                      ← DIO 4, 8, 9, 10 are ON. GPIO11, 12 are configured as
analog inputs
AT+AIO?<CR>
****, ****, 192A, 13E8, ****, ****
                                  \leftarrow AI 2, 3 are used. (GPIO11, 12) The others
are configured as DIO.
OK
```

To get/set the I/O values of the remote devices, remote AT commands can be used as below.

AT+REMOTE=<node ID or IEEE address of a remote node>,<AT command><CR>

### Example)

AT+REMOTE=00019500000F3BA1, AT+DIO?<CR> 10001000111\*\*0000 OK

#### **Periodic Sampling** 5.2.2

The ZE20S can be configured to send its I/O status to a remote device at a periodic rate. To configure this way, please use the AT commands below:

AT+DESTLA=<IEEE address><CR> or AT+DL=<IEEE address><CR>

, where <IEEE address> is the long address of a remote node to send sampled GPIO values of local node.

ATS42=<value><CR>

, where <value> is the GPIO sampling period in seconds. If set to 0, GPIO monitoring is disabled.

ATS43=<value><CR>

, where <value> is the GPIO monitoring node. If set to 0, the monitoring node is selected by AT+DESTLA. If set to is 1, the sink node is set as the monitoring node.

A device can be a sink node by setting S-register 61. The sink node multicasts its address to the other devices in the destination group in the network according to the value of S-register 61, which is called advertising.

ATZ<CR>

Reset the device to apply the changes

The ZE20S can be configured to display periodic sampling data coming from the other nodes. To enable this feature, please use the AT command below:

ATS11=<value><CR>

, where <value> determines whether incoming message will be presented or not. If a user wants to display incoming message in command mode, S11 should be enabled.

If this feature is enabled, incoming message will display in the form of:

++<IEEE address>|<GPIO value><CR>.

ProBee-ZE20S User Guide Rev.1.0.2 46

### **Change Detection Sampling**

The ZE20S module can take an I/O sample and transmit it to a remote device immediately whenever a monitored digital I/O pin changes state. It is possible to configure it with periodic sampling simultaneously. To configure this way, please use the AT commands below:

AT+DESTLA=<IEEE address><CR>

, where <IEEE address> is the long address of a remote node to send sampled GPIO values of local node.

ATS43=<value><CR>

, where <value> is the GPIO monitoring node. If set to 0, the monitoring node is selected by AT+DESTLA. If set to is 1, the sink node is set as the monitoring node.

ATS44=<value><CR>

Set GPIO change detection sampling mode. If <value> is set to 0, GPIO sampling is disabled.

ATZ<CR>

Reset the device to apply the changes

Note: This function applies to only digital I/O.

#### **GPIO Remote Control** 5.2.4

The ZE20S module supports that a local node can change the digital output status by switching digital input pins of a remote node. To use this function, it should be possible for the local node to monitor the GPIO status of the remote node (GPIO monitoring period, S42 > 0) or to detect the GPIO change of the remote node (GPIO change detection sampling mode, S44 = 1). To configure this way, please use the AT commands below:

AT+SOURCELA=<IEEE address><CR> or AT+SL=<IEEE address><CR>

, where <IEEE address> is the long address of a specific source node for changing the status of digital output pin. If this address is set to "FFFFFFFFFFFFFFF", a local node allows that any node can control the GPIO status.

ATS45=<value><CR>

Set GPIO remote control mode. If <value> is set to 0, GPIO control is disabled.

Note: This function applies to only digital I/O.

#### 6 **Working with Development Kit**

The ZE20S development kit provides a quick and easy way to be familiar with the ZE20S and test its functionalities before you build your own PCB board to carry the ZE20S. It is always recommended to start with the ZE20S development kit before your own design.

#### 6.1 **Development Kit Contents**

The development kit consists of ZE20S modules and development boards to carry them. The development board provides RS232 and USB interface to interface with computers and/or your target devices. It provides terminals for digital inputs/outputs and analog inputs, too. It also provides on/off switches and LEDs to simulate and verify digital inputs/outputs. In addition, it has temperature and light sensor so you can test more practical applications. Below is the list of the items included in the package.

- ProBee ZE20S ZigBee OEM Module w/ Chip Antenna (ProBee-ZE20SDC) (1)
- ProBee ZE20S ZigBee OEM Module w/ U.FL Connector (ProBee-ZE20SDU) (1)
- ProBee ZE20S ZigBee OEM Module w/ RPSMA Connector (ProBee-ZE20SDS) (1)
- 3 dBi Dipole Antenna, RP-SMA Plug, Right-hand Thread (2)
- 12cm U.FL to RPSMA Cable, Right-Hand Thread (1)
- Development Boards (3)
- DC Power Adapters (3)
- RS232 Serial Cable (3)
- USB Cable (3)
- AA 1.5V Batteries (12)

#### 6.2 **Development Board Features**

The development board is designed to provide convenient access to the ZE20S interface pins. The development board provides external interfaces as below. Also Figure 6-1 shows the layout of those interfaces of the development board.

- RS232 Interface
- **USB** Interface
- 3 Pre-defined Digital Inputs: Hardware Reset, Factory Default Reset, Permit Joining
- 8 User Configurable Digital Input Buttons
- 8 Digital Outputs with LEDs (Active High)
- 4 Analog Inputs
- Temperature Sensor
- Light Sensor

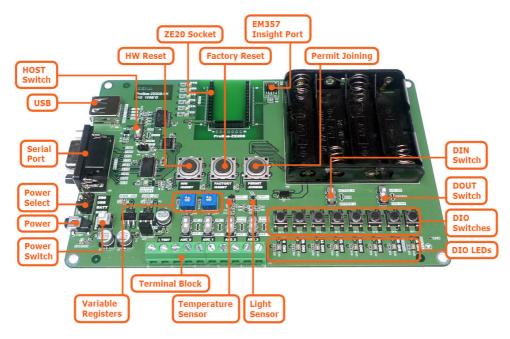


Figure 6-1 Development Board Layout

#### 6.3 **Development Board Hardware Descriptions**

### 6.3.1

There are four ways to supply power to the development board:

- 5V Power Adapter
- **USB Port**
- Batteries (AA 1.5V x 4)
- RS232 Port (5V through 9<sup>th</sup> Pin)

The PWR\_SEL(JP1) jumper MUST be configured properly according to the way to supply power. Table 6-1 shows jumper configuration.

**5V Power Adapter Batteries USB Port RS232 Port** DB9 00 00 00 0 0 SEL **USB** 00 00 0 0 00 PWR 0 0 00 00 00 **BATT** 0 0  $\circ$ 00 DC5V

Table 6-1 Jumpers Configuration

#### 6.3.2 **RS232 Port**

The development board has an RS232 interface for UART communication. The UART\_TXD, UART\_RXD, UART\_DSR (GPIO\_1), UART\_DTR (GPIO\_2), UART\_CTS (GPIO\_3) and UART\_RTS (GPIO\_4) pins of the ZE20S are connected with the RS232 port. To enable the RS232 port, the HOST (SW2) switch should be set to UART.

In addition to the data communication via RS232 port, the RS232 port is capable of supplying power to the development board. In order to use this feature, supply 5V power via the 9<sup>th</sup> pin of the DB9 socket.

### 6.3.3 USB Port

The development board also has a USB interface for UART communication. To use the USB port, the HOST (SW2) switch should be set to USB and the software driver should be installed on the host computer. The installation CD contains the software.

### 6.3.4 ZE20S GPIO Interface

The development board's external GPIO interfaces as well as functional buttons such as factory default reset switches are internally routed to the ZE20S GPIO pins. Table 6-2 summarizes the development board's interfaces and their corresponding GPIO pin numbers of the ZE20S.

Table 6-2 Development Board GPIO Interface Allocation

ZE20S Pin Number	Name	Description	
2	Factory Reset	Factory Default Reset Switch (SW8)	
3	GPIO_0	Permit Joining Switch (SW9)	
4	GPIO_1	UART DTR Output	
5	GPIO_2	UART DSR Input	
6	GPIO_3	UART CTS Input	
7	GPIO_4	UART RTS Output	
22	H/W Reset	Hardware Reset Switch	
23	GPIO_16	Digital Output with LED(CR19) Display (Active High)	
		Digital Input with Button Switch (SW17, Active Low or Active High)	
24	GPIO_15	Digital Output with LED(CR18) Display (Active High)	
		Digital Input with Button Switch (SW16, Active Low or Active High)	
25	UART_RXD	UART Data Input	
26	UART_TXD	UART Data Output	
27	GPIO_14	Digital Output with LED(CR17) Display (Active High)	
		Digital Input with Button Switch (SW15, Active Low or Active High)	
28	GPIO_13	Digital Output with LED(CR16) Display (Active High)	
		Digital Input with Button Switch (SW14, Active Low or Active High)	
29	GPIO_12	Digital Output with LED(CR15) Display (Active High)	
		Digital Input with Button Switch (SW13, Active Low or Active High)	
		Analog Input with Light Sensor (U7)	

30	GPIO_11	Digital Output with LED(CR14) Display (Active High)	
		Digital Input with Button Switch (SW12, Active Low or Active High)	
		Analog Input with Temperature Sensor (U6)	
31	GPIO_10	Digital Output with LED(CR13) Display (Active High)	
		Digital Input with Button Switch (SW11, Active Low or Active High)	
		Analog Input with Variable Register (VR2)	
32	GPIO_9	Digital Output with LED(CR12) Display (Active High)	
		Digital Input with Button Switch (SW10, Active Low or Active High)	
		Analog Input with Variable Register (VR1)	

### 6.3.5 LEDs (CR12-19)

The development board has 8 LEDs for digital output. To enable the LEDs, the GPIO\_OUT (SW20) switch should be set to LED\_ON. The LEDs are turned on when the related GPIO pins of the ZE20S are high.

Note: The ADC\_0~3 switches (SW4~7) should be placed to EXT\_0~3.

### **Button Switches (SW10-17)**

The development board has 8 button switches for digital input. The switches can be configured as active high or active low with the GPIO\_IN (SW19) switch.

Note: The ADC\_0~3 switches (SW4~7) should be placed to EXT\_0~3.

Note: The LED On/Off switch (SW20) should be placed to LED\_OFF.

Note: If the GPIO\_IN (SW19) is set to Active High, GPIO pull up/down option should be set to Pull-Down (ATS41=0). If the GPIO\_IN (SW19) is set to Active Low, GPIO pull up/down option should be set to Pull-Up. (ATS41=1)

### 6.3.7 Variable Resistors (VR1, VR2)

There are two variable resistors for analog inputs on the development board. The analog inputs can be read with the GPIO\_9 and GPIO\_10. To enable the variable resistors, the ADC\_0 and ADC\_1 switches should be placed to VR\_0 and VR\_1.

Note: The LED On/Off switch (SW20) should be placed to LED\_OFF.

#### **Temperature Sensor** 6.3.8

The GPIO\_11 of the ZE20S is routed to the temperature sensor. The relationship between temperature and analog input is as follows:

Temperature( $^{\circ}$ ) ={ Volt( $^{\circ}$ ) -600( $^{\circ}$ )} \* 0.1( $^{\circ}$ C/ $^{\circ}$ NV)

Note: The LED On/Off switch (SW20) should be placed to LED\_OFF.

#### 6.3.9 **Light Sensor**

The GPIO\_12 of the ZE20S is routed to the light sensor. Approximately, the relationship between illumination and analog input is as follows:

Illumination(Lux) = Volt(mV) \* 0.25(Lux/mV)

Note: The LED On/Off switch (SW20) should be placed to LED\_OFF.

### 6.3.10 Terminal Block

The development board has a terminal block for external analog inputs. Figure 6-2 shows the layout of the terminal block. To use external analog inputs instead of the variable resistors, temperature sensor or light sensor, the ADC\_0 (SW4), ADC\_1 (SW5), ADC\_2 (SW6) or ADC\_3 (SW7) should be placed on EXT\_0, EXT\_1, EXT\_2, or EXT\_3.

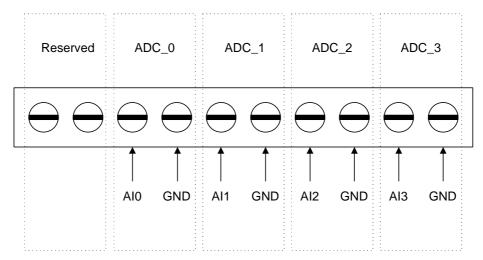


Figure 6-2 Terminal Block for External Anlalog Inputs

Note: The LED On/Off switch (SW20) should be placed to LED\_OFF.

#### 6.4 Configuration Example #1: 1 Coordinator, 1 Router and 1 End-Device

Here is the example configuration to help to start with the ZE20S and the development kit. The goal of this example is to provide hardware configuration and AT commands for the scenario as below:

- One ZE20S module acts as a coordinator and it is connected to a host computer via USB cable.
- One ZE20S module acts as a router and it sends temperature sensor, light sensor and digital inputs to the coordinator every second.
- One ZE20S module acts as a sleepy end-device and it sends temperature sensor, light sensor and digital inputs to the coordinator every second.

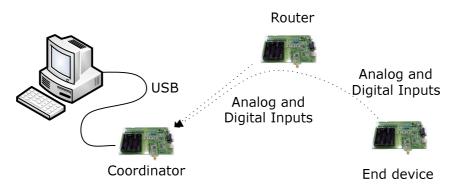


Figure 6-3 Example #1: 1 Coordinator, 1 Router and 1 End-Device

### 6.4.1 Coordinator Configuration

Hardware configuration for the coordinator is as follows:

- Set the HOST switch to USB
- Close the USB\_PWR jumper and open the RS\_PWR and BATT\_PWR jumpers.
- Connect a USB cable between a host computer and the coordinator

The AT commands for the coordinator are as follows:

```
AT+NODETYPE=1
AT+PANID=7772
OK
ATS11=1
OK
AT+LONGADDR
0001950000000001
OK
ATZ
OK
```

#### 6.4.2 **Router Configuration**

Hardware configuration for the coordinator is as follows:

Set the ADC\_2 and ADC\_3 switch to TEMP\_SENS and LIGHT\_SENS

The AT commands for the router are as follows:

```
AT+NODETYPE=2
OK
AT+PANID=7772
```

```
OK
ATS42=1
OK
AT+DESTLA=0001950000000001
OK
AT+GPIO=11111111111441111
OK
ATZ
OK
```

#### **End-device Configuration** 6.4.3

Hardware configuration for the end-device is as follows:

Set the ADC\_2 and ADC\_3 switch to TEMP\_SENS and LIGHT\_SENS

The AT commands for coordinator configuration is as follows:

```
AT+NODETYPE=4
OK
AT+PANID=7772
OK
ATS42=1
OK
AT+DESTLA=0001950000000001
OK
AT+GPIO=11111111111441111
OK
ATZ
OK
```

#### 6.4.4 **Monitoring the Sensors**

Once the configurations are done and the system is running, the terminal (computer) connected to the coordinator will print out the incoming data as follows:

```
++0001950000000002 | 10000000000**0000 | ****, ****, 233E, 006A, ****, ****
++0001950000000003 | 10000000000**0000 | ****, ****, 2254, 0B23, ****, ****
++0001950000000002 | 10000000000**0000 | ****, ****, 2235, 004E, ****, ****
++0001950000000003 | 10000000000**0000 | ****, ****, 226C, 0B8B, ****, ****
```

## Configuration Example #2: 1 Coordinator and 2 End-Devices

Here is another example assuming different system configurations. This example can be described as follows:

- One ZE20S module acts as a coordinator and it is connected to a host computer via serial cable.
- Two ZE20S modules act as end-devices.
- Turn on/off the LEDs of the end-devices remotely through the coordinator

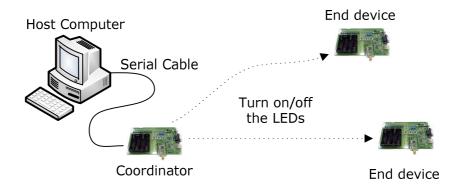


Figure 6-4 Example #2: 1 Coordinator and 2 End-Devices

#### **Coordinator Configuration** 6.5.1

Hardware configuration for the coordinator is as follows:

- Set the HOST switch to UART
- Connect a serial cable between a host computer and the coordinator

The AT commands for coordinator configuration is as follows:

```
AT+NODETYPE=1
OK
AT+PANID=7772
OK
ATZ
OK
```

### **End-devices Configuration**

Hardware configuration for the coordinator is as follows:

Set the GPIO\_OUT switch to LED\_ON

The AT commands for the end-devices are as follows:

```
AT+NODETYPE=4
OK
AT+PANID=7772
```

```
OK
OK
AT+LONGADDR
0001950000000003
OK
ATZ
OK
```

#### 6.5.3 Turning on/off the LEDs

The AT commands to control the LEDs are as follows:

```
OK
```

#### 6.6 Configuration Example #3: Light Sensor and Temperature Sensor

Here is an example sampling light sensor data and temperature sensor data. This example can be described as follows:

- One ZE20S module acts as a coordinator and it is connected to a host computer via serial cable.
- One ZE20S modules act as a router.
- Sampling light sensor data and temperature sensor data in many ways

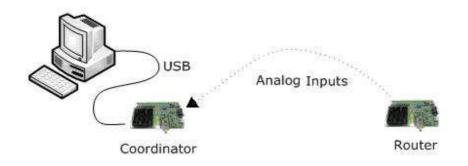


Figure 6-5 Example #3: Light Sensor and Temperature Sensor

### 6.6.1 Coordinator Configuration

Hardware configuration for the coordinator is as follows:

- Set the HOST switch to USB
- Close the USB\_PWR jumper and open the RS\_PWR and BATT\_PWR jumpers.

Connect a USB cable between a host computer and the coordinator

The AT commands for the coordinator are as follows:

```
AT+NODETYPE=1
                        # Set node type as Coordinator
OK
                        # Response
                        # Set 16-bit PAN ID (7772)
AT+PANID=7772
OK
                        # Response
```

### **Router Configuration**

Hardware configuration for the coordinator is as follows:

Set the ADC\_2 and ADC\_3 switch to TEMP\_SENS and LIGHT\_SENS

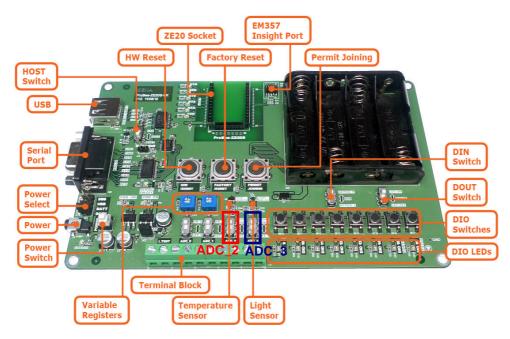


Figure 6-6 Hardware Configuration

The AT commands for the router are as follows:

```
AT+NODETYPE=2
                           # set node type as Router
OK
                           # Response
AT+PANID=7772
                           # Set same 16-bit PAN ID (7772) as Coordinator
OK
                           # Response
AT+GPIO=55555000000440055  # Set ADC_2 and ADC_3 as Analog Input
                           # OR
                           #AT+GPIO11=4 (Set ADC_2 as Analog Input)
```

	#AT+GPI012=4 (Set ADC_3 as Analog Input)
OK	# Response

## 6.6.3 Applying

### **Applying and Confirm of Coordinator**

The AT commands for Applying and Confirm of Coordinator:

ATZ	Apply Coordinator Configuration And	
	# Construct Network	
OK	# Response	
AT+LONGADDR?	# Confirm Long Address of Coordinator	
0001950000001481	# Long Address of Coordinator	
OK	# Response	
AT+OPCH?	# Confirm Network Channel	
20	# Network Channel	
OK	# Response	
AT+OPPANID?	# Confirm Network PAN ID	
7772	# Network PAN ID	
OK	# Response	
AT+SHORTADDR?	# Confirm Network Short Addreess of Coordinator	
0000	# Network Short Address	
OK	# Response	

### 6.6.3.2 Applying and Confirm of Router

The AT commands for Applying and Confirm of Coordinator:

```
ATZ
                        # Apply Router Configuration And Construct Network
OK
                        # Response
AT+LONGADDR?
                        # Confirm Long Address of Router
00019500000000212
                        # Long Address of Router
OK
                        # Response
AT+OPCH?
                        # Confirm Network Channel
20
                        # Network Channel
                        # Response
AT+OPPANID?
                        # Confirm Network PAN ID
7772
                        # Network PAN ID
OK
                        # Response
AT+SHORTADDR?
                        # Confirm Network Short Addreess of Router
```

```
9AD6
                        # Network Short Address
OK
                        # Response
```

#### 6.6.4 **Queried Sampling**

### 6.6.4.1 Getting Analog Data at Router

The AT commands for Getting Analog Data at Router:

```
AT+AI?
                                  # Get all the analog data
****, ****, 2179, ODFE, ****, ****
                                  # Analog Data
   # NA,NA,Termerature,Illumination,NA,NA
   # (Variable Register 0, 1 are set as they are not available)
   # Refer 6.6.7 Data Conversion for Conversion of Analog Data
   # to Temperature and Illumination
OK
                 # Response
AT+AI2?
                 # Get analog data for temperature
2182
                 # Analog data for temperature(Refer to 6.6.7 Data Conversion)
                 # Response
OK
AT+AI3?
                 # Get analog data for illumination
0BF9
                 # Analog data for illumination(Refer to 6.6.7)
OK
                 # Response
```

### 6.6.4.2 Getting Analog Data at Coordinator

The AT commands for Getting Analog Data at Coordinator:

```
AT+REMOTE=0001950000000212, AT+AI?
                 # Get all the analog data of Router from remote Coordinator
****, ****, 2194, ODF3, ****, ****
   # Analog data of Router
   # NA, NA, Temperature, Illumination, NA, NA
   # (Variable Register 0, 1 are set as they are not available)
   # Refer 6.6.7 Data Conversion for Conversion of Analog Data
   # to Temperature and Illumination
OK
                        # Response
AT+REMOTE=9AD6, AT+AI?
              # Get all the analog data of Router from remote coordinator
****, ****, 218F, 0D9A, ****, ****
                        # Analog data of Router
OK
                        # Response
```

```
AT+REMOTE=0001950000000212, AT+AI2?
          # Get router's analog data for temperature from remote coordinator
218F
          # Router's analog data for temperature (Refer to 6.6.7 Data
          # Conversion)
OK
          # Response
AT+REMOTE=9AD6, AT+AI3?
          # Get router's analog data for illumination from remote coordinator
0D8D
          # Router's analog data for illumination (Refer to 6.6.7 Data
          # Conversion)
OK
          # Response
```

#### 6.6.5 Periodic Sampling - Destination Node

### 6.6.5.1 Coordinator Configuration

The AT commands for Coordinator Configuration:

```
ATS11=1
                        # Set coordinator to receive incoming data
OK
                        # Response
ATZ
                        # Apply configuration
OK
                        # Response
```

### 6.6.5.2 Router Configuration

The AT commands for Router Configuration:

```
AT+DESTLA=0001950000001481
                 # Set coordinator to the destination device to send
                 # analog data such as temperature, illumination
OK
ATS42=1
                # Period to send analog data to destination (unit : second)
OK
                # Response
ATS43=0
                # Set destination to AT+DESTLA
                 # ATS43=1 sets destination to sink node
                 # Apply configuration
ATZ
OK
                 # Response
```

## 6.6.5.3 Temperature / Illumination Data at Coordinator

The AT commands for Sampling Temperature / Illumination at Coordinator:

```
++0001950000000212|11000000000**0000|****,****,21D6,0C72,****,****
++0001950000000212 | 110000000000**0000 | ****, ****, 21D0, 0B87, ****, ****
```

```
++0001950000000212|11000000000**0000|****,****,21CB,0324,****,****
                            # Data changes after covering sensors with fingers
++0001950000000212 | 110000000000**0000 | ****, ****, 229B, 0084, ****, ****
++0001950000000212|11000000000**0000|****,****,22A7,009E,****,***
++0001950000000212 | 11100000000**0000 | ****, ****, 22A9, 002D, ****, ****
```

- Data displayed at coordinator every second
- Data format: ++</EEE address>|<GPIO value>|<Analog Input Data>
- Refer to 6.6.7 Data Conversion about how to convert to analog data to temperature and illumination

### 6.6.6 Periodic Sampling - Sink Node

### 6.6.6.1 Coordinator Configuration

The AT commands for Coordinator Configuration:

```
ATS11=1
                    # Set coordinator to receive incoming data
OK
                    # Response
ATS61=10
                    # Set coordinator to sink node which multicasts its
                    # address to the devices in AT+DESTGROUPID every 10 sec.
OK
                    # Response
ATZ
                    # Apply configuration
OK
                    # Response
```

### 6.6.6.2 Router Configuration

The AT commands for Router Configuration:

```
# Reset destination to send analog data (Destination address does not
   # affect on sending analog data to sink node but reset destination to
   # confirm that analog data are sent to sink node)
OK
               # Response
ATS42=1
               # Period to send analog data to sink node (unit : second)
               # Response
OK
ATS43=1
               # Set destination to sink node
               # ATS43=0 sets destination to AT+DESTLA
               # Apply configuration
ATZ
OK
               # Response
```

### 6.6.6.3 Temperature / Illumination Data at Coordinator

The AT commands for Sampling Temperature / Illumination at Coordinator:

```
++0001950000000212|11100000000**0000|****,****,217F,0CD8,****,****
++0001950000000212|11100000000**0000|****,****,217E,0A2D,****,****
++0001950000000212|11100000000**0000|****,****,217F,0D19,****,****
                           # Data changes after covering sensors with fingers
++0001950000000212|11100000000**0000|****,****,2240,007A,****,****
++0001950000000212|11100000000**0000|****,****,22E8,0078,****,****
++0001950000000212|11100000000**0000|****,****,2301,00A6,****,****
```

Refer to 6.6.7 Data Conversion about how to convert to analog data to temperature and illumination

### 6.6.7 Data Conversion

### 6.6.7.1 Analog Data Format

Analog data from temperature sensor and illumination sensor are a combination of 16-bit hexadecimal integer between 0~2EE0(0~1200mV) or D120-FFFF(-1200~-1mV) which unit value corresponds to 0.1 mv.

### 6.6.7.2 Conversion of Analog Data

- Conversion of Analog Data to Actual Voltage If the Value is between 0 ~ 2EE0, Voltage (mV) = Value \* 0.1 If the Value is between D120 ~ FFFF, Voltage (mV) = (Value - 65536) \* 0.1
- Conversion of Actual Voltage to Temperature Temperature( $^{\circ}$ ) ={ Volt( $^{\circ}$ ) -600( $^{\circ}$ )} \* 0.1( $^{\circ}$ C/ $^{\circ}$ N)
- Conversion of Actual Voltage to Illumination Illumination(Lux) = Volt(mV) \* 0.25(Lux/mV)

### **6.6.7.3 Examples**

```
++0001950000000212|11100000000**0000|****,****,217F,0CD8,****,****
++0001950000000212|11100000000**0000|****,****,217E,0A2D,****,****
++0001950000000212|11100000000**0000|****,****,217F,0D19,****,****
                           # Conversion 1
                           # Data changes after covering sensors with fingers
++0001950000000212|11100000000**0000|****,****,2240,007A,****,****
                           # Conversion 2
++0001950000000212|11100000000**0000|****,****,22E8,0078,****,****
++0001950000000212|11100000000**0000|****,****,2301,00A6,****,****
```

Examples show conversion of data at 6.6.6.3 Temperature / Illumination Data at Coordinator.

```
# Conversion 1 (++0001950000000212|11100000000**0000|****,****,217F,0D19,****,****)
[Temperature Conversion]
    Analog Data from Temperature Sensor: 217F (in hexadecimal)
    Analog Data from Temperature Sensor: 8575 (in decimal)
    Actual Voltage: Volt(mV) = 8575 * 0.1 = 857.5(mV)
    Temperature: Temperature(^{\circ}C) = (857.5 – 600) * 0.1 = 25.75(^{\circ}C)
[Illumination Conversion]
    Analog Data from Illumination Sensor: 0D19 (in hexadecimal)
    Analog Data from Illumination Sensor: 3353 (in decimal)
    Actual Voltage: Volt(mV) = 3353 * 0.1 = 335.3(mV)
    Illumination: Illumination(Lux) = 335.3 * 0.25 = 85.83(Lux)
# Conversion 2 (++0001950000000212|11100000000**0000|****,****,2240,007A,****,****)
[Temperature Conversion]
    Analog Data from Temperature Sensor: 2240 (in hexadecimal)
    Analog Data from Temperature Sensor: 8768 (in decimal)
    Actual Voltage: Volt(mV) = 8768 * 0.1 = 876.8 (mV)
    Temperature: Temperature(^{\circ}C) = (876.8 – 600) * 0.1 = 27.68(^{\circ}C)
[Illumination Conversion]
    Analog Data from Illumination Sensor: 007A (in hexadecimal)
    Analog Data from Illumination Sensor: 122 (in decimal)
    Actual Voltage: Volt(mV) = 122 * 0.1 = 12.2(mV)
    Illumination: Illumination(Lux) = 12.2 * 0.25 = 3.05(Lux)
```

#### 7 **AT Command Reference**

#### 7.1 **Command Line Format**

Each command line is composed of a prefix, body and terminator. Only "AT" can be used for the prefix. The body is a string of characters. The terminator is <CR> or <NL>. A command can be one of the followings:

• Read a configuration parameter:

AT<Command>?<CR>

• Do something:

AT<Command><CR>

• Write a configuration parameter:

AT<Command>=<Parameter 1>,<Parameter 2>,<Parameter 3>,...<CR>

Commands denoted with a "+" character are extended AT commands.

S-registers are supported. Multiple commands in the same command line are not supported.

#### **Standard AT Commands** 7.2

#### 7.2.1 ΑT

Description	Check the state of the connection between host and ProBee device.	
Execute	AT <cr></cr>	
Response	OK <cr></cr>	

### 7.2.2 ATB

Description	Enter the broadcast data mode. Every data is packetized at intervals of inter character
Description	timeout (S12) and transmit range is determined by broadcast range (S35).
Execute	ATB <cr></cr>
Response	OK <cr></cr>

### 7.2.3 ATD

	Enter the unicast data mo	ode to specific node. If the	re's no argument after the
Description	command, it will connec	ct to the preconfigured	destination IEEE address
	(AT+DESTLA). Every data is packetized at intervals of inter character timeout (S12).		
Execute	ATD <cr></cr>	ATD <nodeid><cr></cr></nodeid>	ATD <ieee><cr></cr></ieee>
Response	OK <cr> or ERROR<cr></cr></cr>		

## 7.2.4 ATE

Description	Echo(1) or No Echo(0).
Execute	ATE <number><cr></cr></number>
Response	OK <cr></cr>

## 7.2.5 ATM

	Enter the multicast mode. If there's no argument after the command, it will connect to the preconfigured destination group ID(AT+DESTGROUPID). Every data is packetized	
Description		
	at intervals of inter character timeout (S12).	
Execute	ATM <cr></cr>	ATM <groupid><cr></cr></groupid>
Response	OK <cr></cr>	

## 7.2.6 ATO

Description	Return to data mode.
Execute	ATO <cr></cr>
Response	

## 7.2.7 ATR

Description	Response(1) or No Response(0).
Execute	ATR <number><cr></cr></number>
Response	OK <cr></cr>

## 7.2.8 ATS

Description	Get/Set the S-registers.		
Execute	ATS <cr></cr>	ATS <number>?<cr></cr></number>	ATS <number>=<value><cr></cr></value></number>
Response	List of the S-register and	<value><cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
	description	OK <cr></cr>	UNCONS OF ENNORAGES

## 7.2.9 ATZ

Description	Reset the node.
Execute	ATZ <cr></cr>
Response	OK <cr></cr>

## 7.2.10 AT&F

Description	Factory reset.
Execute	AT&F <cr></cr>
Response	OK <cr></cr>

## 7.2.11 +++

Description	Interrupt data mode. "+++" must be entered within 500ms.
Execute	+++
Response	OK <cr></cr>

#### **Node Specific Information** 7.3

## 7.3.1 AT+LONGADDR or AT+LA

Description	Get the 64-bit IEEE address. (EUI address, long address) The IEEE address is a unique device address assigned during manufacturing. This address is unique to each physical device.
Execute	AT+LONGADDR? <cr></cr>
Response	<ieee address=""><cr></cr></ieee>
	OK <cr></cr>

### 7.3.2 AT+SHORTADDR or AT+SA

Description	Get the 16-bit Node ID. (network address, short address) The node ID of "0000" is
	reserved for the coordinator. All other devices receive a randomly generated address
	from the coordinator or router device that allows the join. This value can change if an
	address conflict is detected where two devices are found to have the same address or
	a device leaves the network and later joins.
Execute	AT+SHORTADDR? <cr></cr>
Response	<node id=""><cr></cr></node>
	OK <cr></cr>

### 7.3.3 AT+ADDRDISCOVERY or AT+AD

Description	Get the corresponding address of a node whose long or short address is known.	
Execute	AT+ADDRDISCOVERY= <ieee><cr></cr></ieee>	AT+ADDRDISCOVERY= <nodeid><cr></cr></nodeid>
Response	<node id=""><cr></cr></node>	<ieee address=""><cr></cr></ieee>
	OK <cr></cr>	OK <cr></cr>

## 7.3.4 AT+OPCH or AT+OC

Description	Get the operating channel number used for transmitting and receiving between RF
	modules. Uses 802.15.4 channel numbers. A value of "0" means the device has not
	joined a PAN and is not operating on any channel.
Execute	AT+OPCH? <cr></cr>
Response	<value><cr></cr></value>
	OK <cr></cr>

## 7.3.5 AT+OPPANID or AT+OI

Description	Get the operating 16-bit PAN ID. If PAN ID is set specific value not 0s, operating PAN ID will equal designated PAN ID. A value of "FFFF" means the device is not joined a network.
Execute	AT+OPPANID? <cr></cr>
Response	<value><cr></cr></value>
	OK <cr></cr>

## 7.3.6 AT+OPEPID or AT+OE

Description	Get the operating 64-bit extended PAN ID. A value of "FFFFFFFFFFFFFF" means
	the device is not joined a network.
Execute	AT+OPEPID? <cr></cr>
Response	<value><cr></cr></value>
	OK <cr></cr>

## 7.3.7 AT+VERSION or AT+VR

Description	Get firmware version of the module. The firmware version returns a form of "PTvx.x".
Execute	AT+VERSION? <cr></cr>
Response	<value><cr></cr></value>
	OK <cr></cr>

## 7.3.8 AT+PRODUCTNAME or AT+PN

Description	Get the product name. It can be used to distinguish among different hardware
	platforms.
Execute	AT+PRODUCTNAME? <cr></cr>
Doonanaa	<value><cr></cr></value>
Response	OK <cr></cr>

# 7.4 Network Specific Parameters

### 7.4.1 AT+CHMASK or AT+CM

	Get/Set the channel mask to use. Bits set a	as 1 indicate that this particular channel can
	be used. Bits set as 0 indicate that this particular channel should not be used. For	
Description	example, a channel mask value of 0x00000001 indicates that only channel 0 should be	
	used. Valid channels range from 11 to 26 inclusive. (16 channels are available.) This	
	translates to a channel mask value of "0x07FFF800".	
Execute	AT+CHMASK? <cr></cr>	AT+CHMASK= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK CD, or EDDOD CD.
	OK <cr></cr>	OK <cr> or ERROR<cr></cr></cr>
Default	07FFF800	

Range	00000800 - 07FFF800
-------	---------------------

## 7.4.2 AT+PANID or AT+PI

	Get/Set the 16-bit PAN ID. If it is set to 0s at a coordinator, the coordinator will select a	
Description	random 16-bit hexadecimal number as PAN ID. If it is set to 0s at a router/end-device,	
	the router/end-device will try to join any existing network regardless of PAN ID.	
Execute	AT+PANID? <cr></cr>	AT+PANID= <value><cr></cr></value>
D	<value><cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
Response	OK <cr></cr>	OK-CR > 01 ERROR-CR>
Default	0000	
Range	0000 – FFFF	

## 7.4.3 AT+EPID or AT+EI

Description	Get/Set the 64-bit extended PAN ID. If the node is a coordinator and the EPID is set to	
	0s, it will create new extended PAN ID using its 64-bit IEEE address as extended PAN	
Description	ID. If the node is a router or end-device and the EPID is set to 0x, it will try to join any	
	existing network regardless of extended PAN ID.	
Execute	AT+EPID? <cr></cr>	AT+EPID= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK (CD) or EDDOD (CD)
	OK <cr></cr>	OK <cr> or ERROR<cr></cr></cr>
Default	00000000000000	
Range	0000000000000 - FFFFFFFFFFFFF	

## 7.4.4 AT+GROUPID or AT+GI

Description	Get/Set the 16-bit Group ID. It is used for multicast data reception.	
Execute	AT+GROUPID? <cr></cr>	AT+GROUPID= <value><cr></cr></value>
Response	<value><cr> OK<cr></cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
Default	0000	
Range	0000 - FFFF	

## 7.4.5 AT+POWER or AT+PW

Description	Get/Set the TX power at which the RF module transmits conducted power.	
Execute	AT+POWER? <cr></cr>	AT+POWER= <value><cr></cr></value>
Response	<value><cr> OK<cr></cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
Default	8	
Range	-43 - 8	

## 7.4.6 AT+STACK or AT+ZS

Description	Get/Set the ZigBee stack profile value. This value must be set the same on all devices	
	that should join the same network. (0: Network specific, 1: ZigBee, 2: ZigBee Pro)	
Execute	AT+STACK? <cr></cr>	AT+STACK= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
	OK <cr></cr>	OKCK OF ERRORCES
Default	0	
Range	0 - 2	

### 7.4.7 AT+NODENAME or AT+NN

Description	Get/Set the node name. It can be used to make a clear distinction role or functionality	
	of local node from others.	
Execute	AT+NODENAME? <cr></cr>	AT+NODENAME= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
	OK <cr></cr>	OK <cr> 01 ERROR<cr></cr></cr>
Default	ProBee-ZE	
Range	Up to 16 characters	

## 7.5 Network Formation and Join

## 7.5.1 AT+ASCAN or AT+AS

Description	Perform a scanning for existing network. It can take up to 5 seconds. (CAUTION: It is	
Description	possible to cause a link error if a node is a parent of an end-device.)	
Execute	AT+ASCAN <cr> AT+ASCAN=<channel mask=""><cr></cr></channel></cr>	
	<channel> <pan id=""> <epid> <joinable> <stack profile=""></stack></joinable></epid></pan></channel>	
Response List of the existing networks		
	OK <cr></cr>	

## 7.5.2 AT+ESCAN or AT+ES

	Perform a scanning for energy level of	all channels. It can be used to avoid
Description	interference. It can take up to 5 seconds. The RSSI energy level ranges from approximately -100 to +127 in dBm. ( <i>CAUTION: It is possible to cause a link error if a</i>	
	``	
	node is a parent of an end-device.)	
Execute	AT+ESCAN <cr></cr>	AT+ESCAN= <channel mask=""><cr></cr></channel>
	<channel> <rssi></rssi></channel>	
Response	List of the RSSI for each channel	
	OK <cr></cr>	

## 7.5.3 AT+DSCAN or AT+DS

Description	Perform a scanning for existing nodes in the current network. A coordinator or router can have children nodes and they are presented by "CLDn". It can be possible to place some conditions such as scan duration, node type and node name in order. The information of local node is presented by "*". (CAUTION: A ProBee-Z*10 with PTv1.2 or earlier cannot receive the response of AT+DSCAN from any ProBee-Z*10 with PTv1.3 or later. It cannot receive from any ProBee-Z*20, either. In this case, it is
	recommended to upgrade PTv1.2 to the latest version.)  AT+DSCAN <cr> or</cr>
Execute	AT+DSCANCON of  AT+DSCAN= <scan duration=""><cr> or  AT+DSCAN=<scan duration="">,<node type=""><cr> or  AT+DSCAN=<scan duration="">,<node type="">,<node name=""><cr></cr></node></node></scan></cr></node></scan></cr></scan>
Response	<node type=""> <ieee address=""> <node id=""> <version> <product name=""> <node name=""> List of the existing nodes and information OK<cr></cr></node></product></version></node></ieee></node>
Range	Scan duration: 1 – 10 Node type: 0 – 4 (Zero indicates all node types.)

## 7.5.4 AT+RSSI or AT+RS

Description	Get RSSI and LQI information respectively for the delivery of the recent packet across	
	the last hot of the incoming route. The LQI value ranges from 0 to 255 with the	
	maximum value representing the best possible link quality. The RSSI value ranges	
	from approximately -100 to +127 with each value representing the energy level in dBm	
	at the radio's receiver. The sender of the recent packet and the parent are also	
	displayed.	
Execute	AT+RSSI? <cr></cr>	
Response	Sender: <node id="">, Parent: FFFF, RSSI: <rssi value="">, LQI: <lqi value=""><cr></cr></lqi></rssi></node>	
	OK <cr></cr>	

## 7.5.5 AT+NODETYPE or AT+NT

Description	Get/Set the node type. (0: none, 1: coordinator, 2: router, 3: end-device, 4: sleepy end-device)	
Execute	AT+NODETYPE? <cr></cr>	AT+NODETYPE= <value><cr></cr></value>
Response	<value><cr> OK<cr></cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
Default	0	
Range	0 - 4	

## 7.5.6 AT+PERMIT or AT+PJ

Description	Permit other nodes to join the network. (	(0~254s, 255=continuance) An end-device
	cannot perform it.	
Execute	AT+PERMIT <cr></cr>	AT+PERMIT= <value><cr></cr></value>
Response	OK <cr></cr>	
Range	0 - 255	

## 7.5.7 AT+LEAVE or AT+LV

Description	Leave the current network.
Execute	AT+LEAVE <cr></cr>
Response	OK <cr></cr>

## 7.6 End-device

## 7.6.1 AT+SLEEP or AT+SM

Description	Enter the sleep mode immediately if the node is a sleepy end-device.
Execute	AT+SLEEP <cr></cr>
Response	OK <cr></cr>

## 7.6.2 AT+PARENTLA or AT+PL

Description	Get the 64-bit IEEE address of the parent node.
Execute	AT+PARENTLA? <cr></cr>
Response	<ieee address=""><cr></cr></ieee>
	OK <cr></cr>

## 7.6.3 AT+PARENTSA or AT+PS

Description	Get the 16-bit Node ID of the parent node.
Execute	AT+PARENTSA? <cr></cr>
Response	<node id=""><cr></cr></node>
	OK <cr></cr>

## 7.6.4 AT+CHILDTABLE or AT+CT

Description	Get the child table composed of the end-devices.	
Execute	Execute AT+CHILDTABLE? <cr></cr>	
	<node type=""> <ieee address=""> <node id=""></node></ieee></node>	
Response	List of the child nodes	
	OK <cr></cr>	

## 7.7 Data Transmission and Reception

## 7.7.1 AT+DESTLA or AT+DL

Description	Get/Set the 64-bit destination IEEE address for unicast data transmission.	
Execute	AT+DESTLA? <cr></cr>	AT+DESTLA= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
	OK <cr></cr>	
Default	00000000000000	
Range	0000000000000 - FFFFFFFFFFFFF	

### 7.7.2 AT+DESTGROUPID or AT+DG

Description	Get/Set the 16-bit destination Group ID for multicast data transmission.	
Execute	AT+DESTGROUPID? <cr></cr>	AT+ DESTGROUPID= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
	OK <cr></cr>	
Default	0000	
Range	0000 – FFFF	

## 7.7.3 AT+SINKINFO or AT+SI

Description	Get the long and short addresses of sink node. If there is no sink node in the network,	
	the addresses will be "FFFFFFFFFFFFFF" and "FFFF".	
Execute	AT+SINKINFO? <cr></cr>	
Response	<ieee address="">,<nodeid><cr></cr></nodeid></ieee>	
	OK <cr></cr>	

## 7.7.4 AT+MAXPAYLOAD or AT+MP

Description	Get the maximum size of the payload that the Application Support sub-layer will
	accept. The size depends on the security level in use.
Execute	AT+MAXPAYLOAD? <cr></cr>
Response	<value><cr></cr></value>
	OK <cr></cr>

## 7.7.5 AT+TRASNSMITMODE or AT+TM

	0.40 + 4 + 4 + + + + + + + + + + + + + + +	1
	Get/Set the data transmission mode. This	s mode is maintained after rebooting. (0:
Description	none, 1: unicast to destination long addre	ss, 2: multicast to destination group ID, 3:
	broadcast to all nodes, 4: unicast to sink node)	
Execute	AT+TRANSMITMODE? <cr></cr>	AT+TRANSMITMODE= <value><cr></cr></value>
Deenenee	<value><cr></cr></value>	OK (CD) or EDDOD (CD)
Response	OK <cr></cr>	OK <cr> or ERROR<cr></cr></cr>
Default	0	

Range	0 - 4
3 -	

## 7.7.6 AT+UNICAST or AT+UC

Description	Send unicast message to specific node using long or short address of remote node.	
	Up to 90 bytes (or 72 bytes when security enabled) are sent to the node at once.	
Execute	AT+UNICAST= <ieee>,<data><cr></cr></data></ieee>	AT+UNICAST= <nodeid>,<data><cr></cr></data></nodeid>
Response	OK <cr></cr>	

## 7.7.7 AT+MULTICAST or AT+MC

Description	Send multicast message to specific group. Every node belongs to the group after	
	being booted up if it is designated to a group ID (AT+GROUPID).	
Execute	AT+MULTICAST= <groupid>,<data><cr></cr></data></groupid>	
Response	OK <cr></cr>	

## 7.7.8 AT+BROADCAST or AT+BC

Description	Send broadcast message to the all nodes joining the network. Transmission range is
	determined by broadcast range (S35).
Execute	AT+BROADCAST= <data><cr></cr></data>
Response	OK <cr></cr>

## 7.7.9 AT+REMOTE or AT+RC

Description	Get/Set the configuration values of r AT+REMOTE <cr> shows the list of available.</cr>	remote node using long or short address. ilable commands.
Execute	AT+REMOTE= <addr>,<cmd>?<cr></cr></cmd></addr>	AT+REMOTE= <addr>,<cmd>=<value><cr></cr></value></cmd></addr>
Response	<value><cr> OK<cr></cr></cr></value>	OK <cr></cr>

## 7.8 Security

### 7.8.1 AT+SECURITY or AT+SE

Description	Get/Set the security status. (0: turning security off, 1: on) Every node must be under	
	the same security level in the network.	
Execute	AT+SECURITY? <cr></cr>	AT+SECURITY= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
	OK <cr></cr>	
Default	0	
Range	0 - 1	

## 7.8.2 AT+LINKKEY or AT+LK

Description Get/Set the 128-bit link key. (0 or 0s: generate 128-bit random number)
---

Execute	AT+LINKKEY? <cr></cr>	AT+LINKKEY= <value><cr></cr></value>
Response	<value><cr> OK<cr></cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
Default	FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF	

#### 7.8.3 AT+NWKKEY or AT+NK

Description	Get/Set the 128-bit network key. (0 or 0s: generate random 128-bit number)	
Execute	AT+NWKKEY? <cr> AT+NWKKEY=<value><cr></cr></value></cr>	
Response	<value><cr> OK<cr></cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
Default	FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF	

#### 7.8.4 AT+UPDATEKEY or AT+UK

Description	Update the network key with a new generated key. (possible only for coordinator) It is applied after 30s later because sending too quickly may cause a sleepy end-device to miss the alternate encryption key and only get the switch key message, which means it will be unable to change to the new network key.
Execute	AT+UPDATEKEY <cr></cr>
Response	OK <cr> or ERROR<cr></cr></cr>

# **7.9 UART**

### 7.9.1 AT+BAUDRATE or AT+UB

Description	Get/Set the serial port speed for communication between the module serial port and		
Description	host.		
Execute	AT+BAUDRATE? <cr> AT+BAUDRATE=<value><cr></cr></value></cr>		
Response	<value><cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>	
	OK <cr></cr>		
Default	9600		
Range	300 - 230400		

# 7.9.2 AT+DATABIT or AT+UD

Description	Get/Set the serial data bit setting on the module.		
Execute	AT+DATABIT? <cr> AT+DATABIT=<value><cr></cr></value></cr>		
Response	<pre><value><cr> OK<cr> OK</cr></cr></value></pre> OK		
Default	8		
Range	7 - 8		

### 7.9.3 AT+PARITY or AT+UP

Description	Get/Set the serial parity setting on the module.	
Execute	AT+PARITY? <cr> AT+PARITY=<value><cr></cr></value></cr>	
Response	<pre><value><cr> OK<cr> OK</cr></cr></value></pre>	
Default	0	
Range	0 - 2	

# 7.9.4 AT+STOPBIT or AT+US

Description	Get/Set the serial stop bit setting on the module.	
Execute	AT+STOPBIT? <cr> AT+STOPBIT=<value><cr></cr></value></cr>	
Response	<pre><value><cr> OK<cr> OK</cr></cr></value></pre> OK	
Default	1	
Range	1 - 2	

### 7.9.5 AT+FLOWCTRL or AT+UF

Description	Get/Set flow control status. (0: none, 1: software, 2: hardware flow control)		
Execute	AT+FLOWCTRL? <cr> AT+FLOWCTRL=<value><cr></cr></value></cr>		
Response	<pre><value><cr> OK<cr> or ERROR<cr></cr></cr></cr></value></pre>		
Default	2		
Range	0 - 2		

# 7.10 GPIO

# 7.10.1 AT+GPIO or AT+IO

	Get/Set the configuration status of GPIO individually or all at once. Only GPIO9-14 can		
Description	be set 0-5, others are available 0-3 and 5.		
<b>-</b> .	AT+GPIO? <cr> or</cr>	AT+GPIO= <values><cr> or</cr></values>	
Execute	AT+GPIO <number>?<cr></cr></number>	AT+GPIO <number>=<value><cr></cr></value></number>	
D	<value><cr></cr></value>	OK OD TERROR OD	
Response	OK <cr></cr>	OK <cr> or ERROR<cr></cr></cr>	
Default	55555000000000055		
	GPIO9-14: 0-5, the others: 0-3 and 5		
	0 Disabled (unmonitored digital input)		
Dange	1 Digital input, monitored		
Range	2 Digital output, default low		
	3 Digital output, default high		
	4 Analog input, single ended (only valid for GPIO3~6)		

	5	Reserved for pin-specific alternate functionalities (See Table 5-2)
--	---	---

### 7.10.2 AT+DIO

	Get/Set the digital IO value individually or all at once. All GPIO pins can be used as digital IO and it is only possible to set 0 or 1. If there are some pins used analog input, they are displayed by "*".		
Description			
Execute	AT+DIO? <cr> or</cr>	AT+DIO= <values><cr> or</cr></values>	
Execute	AT+DIO <number>?<cr></cr></number>	AT+DIO <number>=<value><cr></cr></value></number>	
Posponso	<value><cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>	
Response	OK <cr></cr>	ORCOR DI ERRORCOR	
Default	000000000000000		
Range	000000000000000 – 1111111111111111		

# 7.10.3 AT+AI

Description	Get the analog input value individually or all at once. GPIO9~14 are possible to set ADC and it's read only. If there are some pins used digital IO, they are displayed by "****".		
Execute	AT+AI? <cr> AT+AI<number>?<cr></cr></number></cr>		
Dagnanaa	<value>,<value>,<value><cr></cr></value></value></value>	<value><cr></cr></value>	
Response	OK <cr></cr>	OK <cr></cr>	

# 7.10.4 AT+ SOURCELA or AT+SL

Description	Get/Set the 64-bit source IEEE address for GPIO remote control. It is possible to limit on the implementation of this functionality by setting specific address. If set to default value, "FFFFFFFFFFFFFFF," the node allows that any node can control the GPIO status.	
Execute	AT+SOURCELA? <cr></cr>	AT+SOURCELA= <value><cr></cr></value>
Response	<value><cr> OK<cr></cr></cr></value>	OK <cr> or ERROR<cr></cr></cr>
Default	FFFFFFFFFFFF	
Range	0000000000000 – FFFFFFFFFFFF	

# 7.11 Firmware Upload and Help

# 7.11.1 AT+BOOTLOAD or AT+BL

	Start bootloader to upload firmware. (blank: local, 1: passthru)
	The device leaves the AT command line and enters the bootloader menu for uploading
Description	new ProBee firmware. There's no restrict to use local upload but a sleepy end-device
	cannot upload to remote node over the air. The current UART should be set
	115200bps, 8 data bits, no parity, 1 stop bit and none flow control.

Execute	AT+BOOTLOAD <cr></cr>	AT+BOOTLOAD= <number>,<ieee><cr></cr></ieee></number>
		Please start .ebl upload image <cr> or</cr>
	Bootloader menu	Start cloning <cr></cr>
Response		Bootloader menu
	Serial upload complete	
		Bootload Complete!

# 7.11.2 AT+HELP or AT+HP

Description	Show all the available commands
Execute	AT+HELP <cr></cr>
	Available AT Commands
Response	
	OK <cr></cr>

#### **AT Command Examples** 8

#### **Network configuration** 8.1

#### Coordinator

AT+NODETYPE=1<CR> # set node type (coordinator) OK # Response ATZ<CR> # Apply the change OK # Response

#### 8.1.2 **Router**

AT+NODETYPE=2 <cr></cr>	# set node type (router)
OK	# Response
ATZ <cr></cr>	# Apply the change
OK	# Response

#### 8.1.3 End-device

AT+NODETYPE=3 <cr></cr>	#	set node type (end-device)
ок	#	Response
ATZ <cr></cr>	#	Apply the change
OK	#	Response

#### 8.1.4 Sleepy End-device

```
AT+NODETYPE=4<CR>
                               # set node type (sleepy end-device)
OK
                               # Response
ATZ<CR>
                               # Apply the change
OK
                               # Response
```

#### 8.1.5 Specifying Network

```
AT+CHMASK=1000<CR>
                              # set 32-bit channel mask (ch: 12)
                              # Response
AT+PANID=0001 <CR>
                              # set 16-bit PAN ID (0001)
                              # Response
AT+EPID=00000000000000001<CR> # set 64-bit extended PAN ID (000000000000001)
                              # Response
AT+ADDRDISCOVERY=1FEF<CR> # get 64-bit address using 16-bit short address
```

```
00019500002FDC15
OK
                            # Response
AT+REMOTE=1FEF,AT+LONGADDR<CR> # get 64-bit address of remote node (1FEF)
00019500002FDC15
OK
                            # Response
AT+DSCAN<CR>
                            # get the information of other nodes in the network
                            # (Response from ZE10 Node with PTv1.2 or earlier)
ZC* |00019500002FDC40|0000|PTv1.0|ZE10|ZE10_COM3
ZR | 00019500002FDC15 | 1FEF | PTv1.0 | ZE10 | ZE10_COM4
CLD0 | 00019500002FDC17
CLD1 | 00019500002FDC14
ZED | 00019500002FDC17 | 7E34 | PTv1.0 | ZS10 | ZS10_COM5
SED | 00019500002FDC14 | F5AC | PTv1.0 | ZU10 | ZU10_COM6
OK
                            # Response
cf:
AT+DSCAN<CR>
                            # get the information of other nodes in the network
                            # (Response from ZE10 Node with PTv1.3 or later
                            # or ZE20 Node)
```

```
ZC* |00019500002FDC40|0000|PTv1.3|ZE20S|ZE20S_COM3
ZR | 00019500002FDC15 | 1FEF | PTv1.3 | ZE20S | ZE20S_COM4
CLD0 | 7E34
CLD1 | F5AC
ZED | 00019500002FDC17 | 7E34 | PTv1.3 | ZS10 | ZS10 COM5
SED | 00019500002FDC14 | F5AC | PTv1.3 | ZU10 | ZU10_COM6
OK
                               # Response
```

#### **Data Transmission** 8.2

#### 8.2.1 Command Mode

```
# send unicast message(MSG01) to specific node using 64-bit long
address(0x00019500002FDC15)
AT+UNICAST=00019500002FDC15, MSG01<CR>
                              # Response
# send unicast message(MSG02) to specific node using 16-bit short
address(0x1FEF)
AT+UNICAST=1FEF, MSG02<CR>
OK
                              # Response
# send multicast message(MSG03) to specific group(0001)
```

```
AT+MULTICAST=0001, MSG03<CR>
OK
                               # Response
\# send broadcast message(MSG04) to current network and the range is
determined by S35.
AT+BROADCAST=MSG04<CR>
OK
                               # Response
```

#### 8.2.2 Data Mode

```
ATD<CR>
                    # enter the unicast mode using destination long address
OK
                    # Response
MSG05+++
                    # send data(MSG05) and leave data mode
ATD0000<CR>
                       # enter the unicast mode using 16-bit short address
OK
                       # Response
MSG06+++
                       # send data(MSG06) and leave data mode
ATD00019500002FDC40<CR>
                           # enter the unicast mode using 64-bit long address
OK
                       # Response
MSG07+++
                       # send data(MSG07) and leave data mode
ATM<CR>
                       # enter the multicast mode using destination group ID
OK
                       # Response
MSG08+++
                       # send data(MSG08) and leave data mode
ATM0001<CR>
                       # enter the multicast mode using 16-bit group ID
OK
                       # Response
                       # send data(MSG09) and leave data mode
MSG09+++
                       # enter the broadcast mode
ATB<CR>
OK
                       # Response
                       # send data(MSG10) and leave data mode
MSG10+++
AT+TRANSMITMODE=1<CR> # set transmission mode
OK
                       # Response
ATZ<CR>
                       # Apply the change
OK
                       # Response
                        # send data(MSG11) and leave data mode
MSG11+++
ATO<CR>
                        # return to the current data mode
```

#### 8.3 Security

```
AT+SECURITY=1<CR>
                            # set security level (ON)
OK
                            # Response
```

AT+LINKKEY=5A46...21<CR> # set the 128-bit trust center link key (5A46...21)

ATZ<CR> # Apply the change

OK # Response

AT+NWKKEY=0<CR> # set the 128-bit network key (random key)

# Response

AT+UPDATEKEY<CR> # update the changed network key

OK # Response

#### **UART Settings** 8.4

AT+BAUDRATE=115200<CR> # set baud rate (115,200bps)

OK # Response

# set data bit (8bit) AT+DATABIT=8<CR>

# Response

AT+PARITY=0<CR> # set parity (none)

# Response

AT+STOPBIT=1<CR> # set stop bit (1bit)

# Response

AT+FLOWCTRL=2<CR> # set flow control (hardware)

OK # Response

ATZ<CR> # Apply the change

OK # Response

#### **GPIO** 8.5

AT+GPIO=55003300000441122<CR> # set GPIO configuration

OK # Response

ATZ<CR> # Apply the change

OK # Response

AT+GPIOO<CR> # check the current GPIO status (GPIO0)

OK # Response

AT+DIO<CR> # check the current DIO value

10000000000\*\*0011

OK # Response

AT+AI<CR> # check the current AI value

\*\*\*\*, \*\*\*\*, 2EEO, 2EEO, \*\*\*\*, \*\*\*\*

OK # Response

#### 8.6 **Firmware Upload**

#### 8.6.1 Local Node

# enter the bootloader menu for uploading firmware. Note that UART of local node should be set to 115200-8-N-1-N. AT+BOOTLOAD<CR> Press ENTER... SENA ProBee Bootloader v1.0 1. Upload Firmware 2. Run 3. View Firmware info PROBEE > # press "1" and upload ebl file by X-modem begin upload CCCCCCCCCCC Serial upload complete # press "2" or reset after upload is done

#### 8.6.2 Remote Node

# upload firmware to a remote node using 64-bit long address. Note that UART of local node should be set to 115200-8-N-1-N. AT+BOOTLOAD=1,00019500002FDC40<CR> Please start .ebl upload image ... CCCCCCCCCCC # upload ebl file by X-modem Bootload Complete! # succeed to upload

#### 9 S-Registers

Register number	Descriptions	
11	Display incoming message in command mode	
12	Display command echo	
13	Display command responses	
14	Manage LED status	
21	Inter character timeout	
22	Permit joining timeout	
23	TX power mode	
31	Enable application-ACK	
32	Transmission retries	
33	Transmission timeout	
34	Indirect transmission timeout	
35	Broadcast range	
36	Number of hops for multicast/broadcast	
37	Number of hops of nonmembers for multicast	
38	Receive local message for multicast/broadcast	
39	Receive message by own data mode	
41	GPIO pull-up	
42	GPIO monitoring period	
43	GPIO monitoring node	
44	GPIO change detection sampling	
45	GPIO remote control	
51	Poll timeout for a parent node	
52	Poll period for a sleepy end-device	
53	Sleep duration	
54	Standby timeout	
55	Rejoin timeout	
56	Poll period for an end-device	
61	Sink advertise period	
62	Many to one route request period	

#### 9.1 **Display Options**

# 9.1.1 S11

Description	Get/Set the display mode. It determines t mode.	to display incoming message in command
Execute	ATS11? <cr></cr>	ATS11= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr></cr>

	OK <cr></cr>	
Default	0	
Range	0 - 1	

# 9.1.2 S12

Description	Get/Set the command echo mode.		
Execute	ATS12? <cr> ATS12=<value><cr></cr></value></cr>		
Bassassa	<value><cr></cr></value>	OK <cr></cr>	
Response	OK <cr></cr>	UK <cr></cr>	
Default	1		
Range	0 – 1		

# 9.1.3 S13

Description	Get/Set the command responses mode.	
Execute	ATS13? <cr> ATS13=<value><cr></cr></value></cr>	
Response	<value><cr> OK<cr></cr></cr></value>	OK <cr></cr>
Default	1	
Range	0 - 1	

### 9.1.4 S14

	Get/Set the LED mode. It causes the LED operation if the device is ZE20S set GPIO15, 16 to specific functionality.  0: LEDs are always OFF regardless of configuration or status.		
Description			
	1: LEDs are OFF when the node is under sleep status.		
	2: LEDs always operate by the case.		
Execute	ATS14? <cr></cr>	ATS14= <value><cr></cr></value>	
Posponso	<value><cr></cr></value>	OK <cr></cr>	
Response	OK <cr></cr>	ORCR>	
Default	1		
Range	0 - 2		

# 9.2 Network Settings

### 9.2.1 S21

0.2 02.		
Description	Get/Set the inter character timeout in milliseconds. It determines to send data packet	
Description	after this time.	
Execute	ATS21? <cr></cr>	ATS21= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr></cr>

	OK <cr></cr>	
Default	100	
Range	0 - 10000	

# 9.2.2 S22

	Get/Set the timeout to permit joining. It determines the time in seconds that the deview will allow other devices to join to it when it starts network but an end-device cannot be seen to	
Description		
	perform it. If set to 255, the device will always permit joining.	
Execute	ATS22? <cr></cr>	ATS22= <value><cr></cr></value>
Boononco	<value><cr></cr></value>	OK <cr></cr>
Response	OK <cr></cr>	
Default	255	
Range	0 - 255	

# 9.2.3 S23

Description	Get/Set the power boost mode of the module. If enabled, boost mode improv	
	sensitivity and increases output power, improving the link margin and range.	
Execute	ATS23? <cr></cr>	ATS23= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr></cr>
	OK <cr></cr>	UNCUN>
Default	0	
Range	0 – 1	

#### **Data Transmissions** 9.3

# 9.3.1 S31

	Get/Set the application-ACK mode. If it is enabled, a sender node retransmits data packet when it fails to receive ACK from receiver node. This value must be set same on the source and destination node for data transmission.	
Description		
Execute	ATS31? <cr></cr>	ATS31= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr></cr>
	OK <cr></cr>	UK <uk></uk>
Default	1	
Range	0 - 1	

### 9.3.2 S32

	Get/Set the transmission retries. A sender	r tries to retransmit up to this value when
Description	transmission fails. (CAUTION: It is recommended to set the smallest value that the	
	application can tolerate in broadcast/multica	ast data transmission.)
Execute	ATS32? <cr></cr>	ATS32= <value><cr></cr></value>

Response	<value><cr> OK<cr></cr></cr></value>	OK <cr></cr>
Default	5	
Range	0 – 99	

### 9.3.3 S33

	Get/Set the transmission timeout in milliseconds. A sender retransmits data packet after this time when transmission fails. (CAUTION: It is recommended to set this value more than 1000 in broadcast/multicast data transmission.)	
Description		
Execute	ATS33? <cr></cr>	ATS33= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr></cr>
	OK <cr></cr>	UNCON>
Default	500	
Range	0 – 10000	

# 9.3.4 S34

Description	Get/Set the indirect transmission timeout in milliseconds. It is the maximum amount of	
Description	time that the MAC will hold a message for indirect transmission to a child.	
Execute	ATS34? <cr> ATS34=<value><cr></cr></value></cr>	
Response	<value><cr></cr></value>	OK -CD-
	OK <cr></cr>	OK <cr></cr>
Default	3000	
Range	0 – 30000	

# 9.3.5 S35

Description	Get/Set the broadcast range. ZigBee specifies three different broadcast addresses that reach different collections of nodes. Broadcasts are normally sent only to routers. Broadcasts can also be forwarded to end-devices, either all of them or only those that do not sleep. Broadcasting to sleepy end-devices is both significantly more resource-intensive and significantly less reliable than broadcasting to routers.	
	0: send to all routers	
	1: send to all non-sleepy nodes	
	2: send to all nodes in the network	
Execute	ATS35? <cr></cr>	ATS35= <value><cr></cr></value>
Deenenee	<value><cr></cr></value>	OK (CD)
Response	OK <cr></cr>	OK <cr></cr>
Default	2	
Range	0 – 2	

### 9.3.6 S36

	Get/Set the maximum number of hops the message will be relayed. The message will be delivered to all nodes within this number of hops of the sender. A value of zero is converted to maximum value(30). It is used to multicast/broadcast.	
Description		
Execute	ATS36? <cr></cr>	ATS36= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK CD:
	OK <cr></cr>	OK <cr></cr>
Default	0	
Range	0 – 10	

# 9.3.7 S37

Description	Get/Set the number of hops that the message will be forwarded by devices that are not	
Description	members of the group. A value of zero, 7 or greater is treated as infi	
Execute	ATS37? <cr> ATS37=<value><cr></cr></value></cr>	
Response	<value><cr></cr></value>	OK <cr></cr>
	OK <cr></cr>	
Default	0	
Range	0 – 7	

### 9.3.8 S38

Description	Get/Set the receive message mode. If it is enabled, a local node will receive multicast	
Description	or broadcast messages from itself.	
Execute	ATS38? <cr></cr>	ATS38= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr></cr>
	OK <cr></cr>	
Default	0	
Range	0 – 1	

### 9.3.9 S39

Description	Get/Set the receive mode. If S39 is enabled, a local node will only receive the same type of messages with its transmission mode. For example, if local node's transmission mode is broadcast mode (AT+TM=3), it will receive only broadcast	
messages and won't receive unicast or multicast m		ticast messages.
Execute	ATS39? <cr></cr>	ATS39 = <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr></cr>
	OK <cr></cr>	
Default	0	
Range	0 - 1	

### 9.4 **GPIO**

# 9.4.1 S41

Description	Get/Set the GPIO pull up/down option. If GPIOs are set to DI(Digital Input), it is	
Description	possible to pull-up or pull-down with this value. Pull-down = 0, Pull-up = 1.	
Execute	ATS41? <cr></cr>	ATS41= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr></cr>
	OK <cr></cr>	UK <uk></uk>
Default	0	
Range	0 - 1	

### 9.4.2 S42

	Get/Set the GPIO monitoring period in seconds. If it is enabled, a node sends GPIO	
	values to a remote node based on preconfigured destination IEEE address periodically	
Description	and it is possible to monitor the GPIO status at the remote node. A remote node can	
	also be the sink node according to GPIO monitoring node (S43). If set to 0, GPIO	
	monitoring is disabled.	
Execute	ATS42? <cr></cr>	ATS42= <value><cr></cr></value>
Boononco	<value><cr></cr></value>	OK <cr></cr>
Response	OK <cr></cr>	UK <uk></uk>
Default	0	
Range	0 – 10000	

# 9.4.3 S43

Description	Description Get/Set the GPIO monitoring node. If S43 is 0, the monitoring node is selected AT+DESTLA or AT+DL command. If S43 is 1, the sink node is set as the monitoring node.	
Execute	ATS43? <cr></cr>	ATS43= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr></cr>
	OK <cr></cr>	
Default	0	
Range	0 – 10000	

# 9.4.4 S44

	Get/Set the GPIO change detection sampling mode. If it is enabled, a node sends	
	GPIO values to a remote node based on preconfigured destination IEEE address	
Description	on immediately when the status of GPIO changes. A remote node can also be the	
	node according to GPIO monitoring node	(S43). If set to 0, GPIO change detection
	sampling is disabled.	
Execute	ATS44? <cr></cr>	ATS44= <value><cr></cr></value>

Response	<value><cr> OK<cr></cr></cr></value>	OK <cr></cr>
Default	0	
Range	0 – 1	

### 9.4.5 S45

	Get/Set the GPIO remote control mode. If any GPIO pin is set to digital input, a node	
	can control the I/O status of a remote node if the I/O pin of the remote node is set to	
Description	digital output. It is possible to use when GPIO monitoring is enabled (GPIO monitoring	
	period, S42 > 0) or GPIO change detection sampling is enabled.(GPIO change	
	detection sampling mode, S44 = 1)	
Execute	ATS45? <cr></cr>	ATS45= <value><cr></cr></value>
Rosponso	<value><cr></cr></value>	OK <cr></cr>
Response	OK <cr></cr>	UK <ck></ck>
Default	0	
Range	0 – 1	

# 9.5 End-Device

### 9.5.1 S51

Get/Set the poll timeout for a parent node in se		e in seconds. If an end-device or a sleepy
Description	· ·	o its parent coordinator or router within the
	poll timeout, the end-device is removed from the child table.	
Execute	ATS51? <cr></cr>	ATS51= <value><cr></cr></value>
Desmana	<value><cr></cr></value>	OK <cr></cr>
Response	OK <cr></cr>	
Default	60	
Range	0 – 4177920	

# 9.5.2 S52

Description	Get/Set the sleepy end-device poll period in milliseconds. Adaptive polling may allow	
Description	the sleepy end-device to poll more rapidly for a short time when receiving RF data.	
Execute	ATS52? <cr></cr>	ATS52= <value><cr></cr></value>
Response	<value><cr></cr></value>	OK <cr></cr>
	OK <cr></cr>	UK <uk></uk>
Default	100	
Range	0 - 10000	

# 9.5.3 S53

Description	Get/Set the sleep duration in quarter seconds. An end-device sleeps for this time and
-------------	---

	turns off radio every sleep cycle. If a node sleeps over poll timeout of parent node, the	
	device will be removed from the child table.	
Execute	ATS53? <cr> ATS53=<value><cr></cr></value></cr>	
Response	<value><cr></cr></value>	OK <cr></cr>
	OK <cr></cr>	
Default	8	
Range	0 – 16711680	

# 9.5.4 S54

	Get/Set the standby timeout in seconds. When an end-device wakes up and polls with		
Description	the parent node, the node will wait for another data from the ZigBee network or from		
	the serial port for S54 before it goes to sleep mode again. If any serial or RF data is		
	sent or received, the timer will reset and wait for next again.		
Execute	ATS54? <cr></cr>	ATS54= <value><cr></cr></value>	
Response	<value><cr></cr></value>	OK <cr></cr>	
	OK <cr></cr>		
Default	5		
Range	0 – 10000		

# 9.5.5 S55

Description	Get/Set the rejoin timeout. If it is enabled, an end-device tries to rejoin the current		
	network when contact with the network has been lost for setting value in seconds. The		
Description	most common usage case is when an end-device can no longer communicate with its		
	parent and wishes to find a new one.		
Execute	ATS55? <cr></cr>	ATS55= <value><cr></cr></value>	
Posponso	<value><cr></cr></value>	OK <cr></cr>	
Response	OK <cr></cr>		
Default	10		
Range	0 – 10000		

### 9.5.6 S56

Description	Get/Set the end-device poll period in seconds. Adaptive polling may allow the end-		
	device to poll more rapidly for a short time when receiving RF data.		
Execute	ATS56? <cr> ATS56=<value><cr></cr></value></cr>		
Response	<value><cr></cr></value>	OK <cr></cr>	
	OK <cr></cr>		
Default	5		
Range	0 - 10000		

#### 9.6 Sink

### 9.6.1 S61

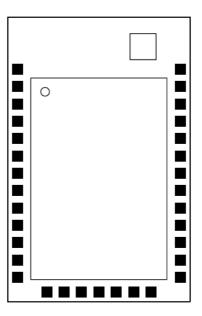
	Get/Set the sink node and the sink advertise period in seconds. When a node is		
Description	defined as a sink, it can multicast its address to the rest of the network in this period. If		
	set to 0, sink advertise is disabled.		
Execute	ATS61? <cr> ATS61=<value><cr></cr></value></cr>		
Doggoogo	<value><cr></cr></value>	OK <cr></cr>	
Response	OK <cr></cr>		
Default	0		
Range	0 – 10000		

### 9.6.2 S62

	Get/Set the period to send Many-to-One Route Request. Many-to-One Route Request		
Description	(MTOR) creates routes from every node in the network back to this node. It is useful		
	when this node acts as a sink node.		
Execute	ATS62? <cr> ATS62=<value><cr></cr></value></cr>		
Posponso	<value><cr></cr></value>	OK <cr></cr>	
Response	OK <cr></cr>		
Default	0		
Range	0 – 10000		

# 10 Pin Assignments

NO	Pin Assignment
1	GND
2	PC_5/FACTORY_RST
3	PC_6/GPIO0
4	PC_7/DTR/GPIO1
5	PA_7/DSR/GPIO2
6	PB_3/CTS/GPIO3
7	PB_4/RTS/GPIO4
8	PA_0/MOSI/GPIO5
9	PA_1/MISO/GPIO6
10	PA_2/SCLK/GPIO7
11	PA_3/nSSEL/GPIO8
12	VCC
13	GND



Pin Assignment	NO
GND	33
PB_5/ADC0/GPIO9	32
PB_6/ADC1/GPIO10	31
PB_7/ADC2/GPIO11	30
PC_1/ADC3/GPIO12	29
PA_4/ADC4/GPIO13	28
PA_5/ADC5/GPIO14	27
PB_1/TXD	26
PB_2/RXD	25
PB_0/GPIO15	24
PA_6/GPIO16	23
/RESET	22
GND	21



Figure 10-1 Pin Assignments

Table 10-1 Pin Assignments Table

Pin	NAME	Default Function	Direction	Description
1	GND	-	-	Ground
2	Factory Reset	Factory Reset	IN	Digital I/O, Factory reset input, Active low
3	GPIO_0	DIO_0	IN/OUT	Digital I/O, Permit joining input
4	GPIO_1	DIO_1	IN/OUT	Digital I/O, UART_DTR
5	GPIO_2	DIO_2	IN/OUT	Digital I/O, UART_DSR
6	GPIO_3	DIO_3	IN/OUT	Digital I/O, UART_CTS
7	GPIO_4	DIO_4	IN/OUT	Digital I/O, UART_RTS
8	GPIO_5	DIO_5	IN/OUT	Digital I/O
9	GPIO_6	DIO_6	IN/OUT	Digital I/O
10	GPIO_7	DIO_7	IN/OUT	Digital I/O
11	GPIO_8	DIO_8	IN/OUT	Digital I/O
12	VCC	-	IN	Power supply, 3.3V
13	GND	-	-	Ground
14	VCC	-	-	Power supply, 3.3V
15	JTCK	-	IN	JTAG clock input from debugger
16	JTDO	-	OUT	JTAG data output to debugger
17	JTDI	-	IN	JTAG data input from debugger
18	JTMS	-	IN	JTAG mode select from debugger
19	JRST	-	IN	JTAG reset input from debugger
20	GND	-	-	Ground
21	GND	-	-	Ground
22	/RESET	-	IN	H/W_/Reset, Active low
23	GPIO_16	DIO_16	IN/OUT	Digital I/O, Status LED
24	GPIO_15	DIO_15	IN/OUT	Digital I/O, Power LED
25	UART_RXD	UART_RXD	IN	UART Data Input
26	UART_TXD	UART_TXD	OUT	UART Data Output
27	GPIO_14	DIO_14	IN/OUT	Digital I/O / ADC_5
28	GPIO_13	DIO_13	IN/OUT	Digital I/O / ADC_4
29	GPIO_12	DIO_12	IN/OUT	Digital I/O / ADC_3
30	GPIO_11	DIO_11	IN/OUT	Digital I/O / ADC_2
31	GPIO_10	DIO_10	IN/OUT	Digital I/O / ADC_1
32	GPIO_9	DIO_9	IN/OUT	Digital I/O / ADC_0
33	GND	-	-	Ground

#### 11 **Connections**

### 11.1 Serial Port Pin Outs

ProBee-ZE20S is a DCE device compatible with the RS232 standard, a DB9 female interface.

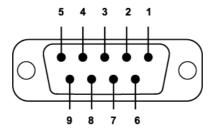


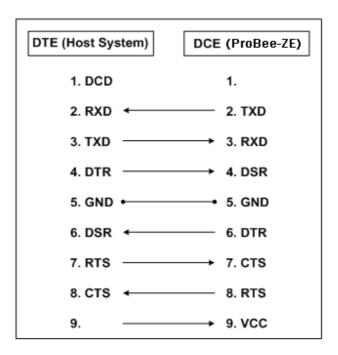
Figure 11-1 Pin layout of the DB-9 female connector

Table 11-1 Pin assignment of the DB-9 female connector

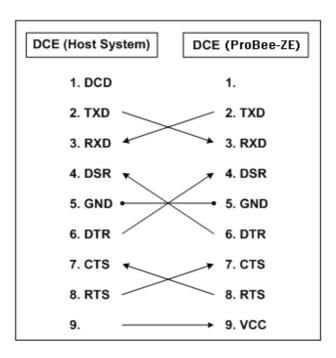
Pin#	Signal	Direction	Description
1	-	-	-
2	TxD	Output	Transmitted Data
3	RxD	Input	Received Data
4	DSR	Input	Data set ready
5	GND	-	Signal Ground
6	DTR	Output	Data terminal ready
7	CTS	Input	Clear to Send
8	RTS	Output	Ready to send
9	VCC	Input	(5V ~ 12V)

# 11.2 Serial Wiring Diagram

#### 11.2.1 To Host with DTE Interface



#### 11.2.2 To Host with DCE Interface



#### **Mechanical Drawings** 12

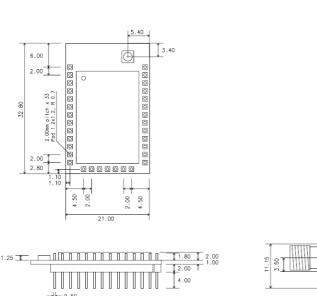


Figure 11-1 ProBee-ZE20SDU

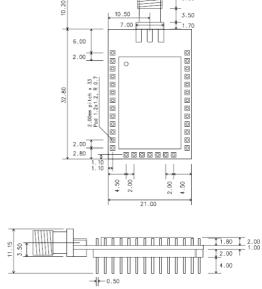


Figure 11-2 ProBee-ZE20SDS

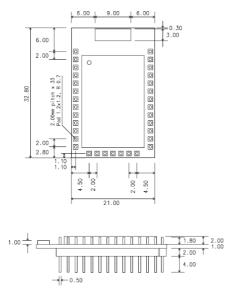


Figure 11-3 ProBee-ZE20SDC

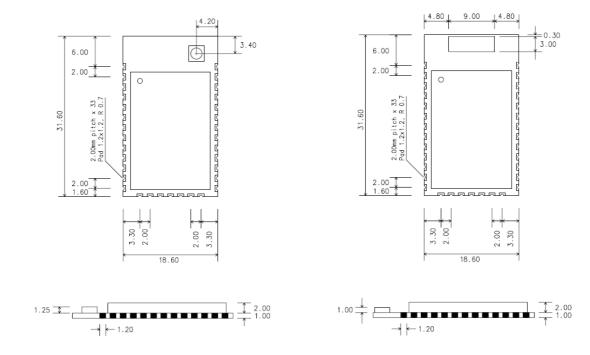


Figure 11-4 ProBee-ZE20SSU

Figure 11-5 ProBee-ZE20SSC

#### 13 Warranty

#### **GENERAL WARRANTY POLICY**

Sena Technologies, Inc. (hereinafter referred to as SENA) warrants that the Product shall conform to and perform in accordance with published technical specifications and the accompanying written materials, and shall be free of defects in materials and workmanship, for the period of time herein indicated, such warranty period commencing upon receipt of the Product.

This warranty is limited to the repair and/or replacement, at SENA's discretion, of defective or nonconforming Product, and SENA shall not be responsible for the failure of the Product to perform specified functions, or any other non- conformance caused by or attributable to: (a) any misapplication or misuse of the Product; (b) failure of Customer to adhere to any of SENA's specifications or instructions; (c) neglect of, abuse of, or accident to, the Product; or (d) any associated or complementary equipment or software not furnished by SENA.

Limited warranty service may be obtained by delivering the Product to SENA or to the international distributor it was purchased through and providing proof of purchase or receipt date. Customer agrees to insure the Product or assume the risk of loss or damage in transit, to prepay shipping charges to SENA, and to use the original shipping container or equivalent.

#### 13.2 LIMITATION OF LIABILITY

EXCEPT AS EXPRESSLY PROVIDED HEREIN, SENA MAKES NO WARRANTY OF ANY KIND, EXPRESSED OR IMPLIED, WITH RESPECT TO ANY EQUIPMENT, PARTS OR SERVICES PROVIDED PURSUANT TO THIS AGREEMENT, INCLUDING BUT NOT LIMITED TO THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. NEITHER SENA NOR ITS DEALER SHALL BE LIABLE FOR ANY OTHER DAMAGES, INCLUDING BUT NOT LIMITED TO DIRECT, INDIRECT, INCIDENTAL, SPECIAL OR CONSEQUENTIAL DAMAGES, WHETHER IN AN ACTION IN CONTRACT OR TORT (INCLUDING NEGLIGENCE AND STRICT LIABILITY), SUCH AS, BUT NOT LIMITED TO, LOSS OF ANTICIPATED PROFITS OR BENEFITS RESULTING FROM, OR ARISING OUT OF, OR IN CONNECTION WITH THE USE OF FURNISHING OF EQUIPMENT, PARTS OR SERVICES HEREUNDER OR THE PERFORMANCE, USE OR INABILITY TO USE THE SAME, EVEN IF SENA OR ITS DEALER HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES, IN NO EVENT WILL SENA OR ITS DEALERS TOTAL LIABILITY EXCEED THE PRICE PAID FOR THE PRODUCT.

#### 13.3 HARDWARE PRODUCT WARRANTY DETAILS

WARRANTY PERIOD: SENA warranties embedded hardware Product for a period of one (1) year, and external hardware Product for a period of three (3) or five (5) years according to the Product type.

WARRANTY PROCEDURE: Upon return of the hardware Product SENA will, at its option, repair or replace Product at no additional charge, freight prepaid, except as set forth below. Repair parts and replacement Product will be furnished on an exchange basis and will be either reconditioned or new. All replaced Product and parts become the property of SENA. If SENA determines that the Product is not under warranty, it will, at the Customers option, repair the Product using current SENA standard rates for parts and labor, and return the Product at no charge in or out of warranty.

#### WARRANTY EXCLUSIONS: Damages caused by

- Accidents, falls, objects striking the SENA product,
- Operating the Product in environments that exceed SENA's temperature and humidity specifications,
- Power fluctuations, high voltage discharges,
- Improper grounding, incorrect cabling,
- Misuse, negligence by the customer or any other third party,
- Failure to install or operate the product (s) in accordance to their SENA User Manual,
- Failure caused by improper or inadequate maintenance by the customer or any other third party,
- Floods, lightning, earthquakes,
- Water spills,
- Replacement of parts due to normal wear and tear,
- Hardware has been altered in any way,
- Product that has been exposed to repair attempts by a third party without SENA's written consent,
- Hardware hosting modified SENA Software, or non-SENA Software, unless modifications have been approved by Sena.
- Battery component capacity degradation due to usage, aging, and with some chemistry, lack of maintenance.

#### 13.4 SOFTWARE PRODUCT WARRANTY DETAILS

WARRANTY PERIOD: SENA warranties software Product for a period of one (1) year.

WARRANTY COVERAGE: SENA warranty will be limited to providing a software bug fix or a software patch, at a reasonable time after the user notifies SENA of software non-conformance.

#### THIRD-PARTY SOFTWARE PRODUCT WARRANTY DETAILS

The warranty policy of the third-party software is conformed to the policy of the corresponding vendor.

#### **Regulatory Information** 14

#### 14.1 FCC

FCC Rule: Part 15 Subpart C Section 15.247

FCCID: S7AIW01

#### **FCC Compliance Statement**

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) This device must accept any interference received,

Including interference that may cause undesired operation

#### Information to User

This equipment has been tested and found to comply with limits for a Class B digital device, Pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation.

This equipment generate, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications.

However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by on or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver-Connect the equipment into an outlet a circuit different form that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

#### **RF Exposure Statement**

The equipment complies with FCC RF radiation exposure limits set forth for an uncontrolled environment. This device and its antenna must not be co-located or operation in conjunction with any other antenna or transmitter.

#### Do not

Any changes or modifications to the equipment not expressly approved by the party responsible for compliance could void user's authority to operate the equipment.

#### 14.2 CE

CE1177(!)

We, Sena Technologies, Inc., declare that the product(s):

ProBee-ZE20S ZigBee OEM Module

to which this declaration relates is in conformity with the following standard(s) or other normative document(s)

- EN 60950-1
- ETSI EN 301 489-1
- ETSI EN 301 489-17
- ETSI EN 300 328

Following the provisions of

• EMC DIRECTIVE 1999/5/EC

#### **14.3 TELEC**

Technical Regulations for Specified Radio Equipment Article 2, Section 1 (19) Certification No:

ProBee-ZE20SDU: 010WWBT0090 ProBee-ZE20SDS: 010WWBT0091 • ProBee-ZE20SDC: 010WWBT0092

#### 14.4 KCC

Type Registration

Certification No: KCC-CRM-SNA-IW01 Basic Model Number: ProBee-ZE20SDU

Series Model Number: ProBee-ZE20SDS, ProBee-ZE20SDC, ProBee-ZE20SSU, ProBee-ZE20SSC

# 15 RF Information

# **Radio Frequency Range**

2.405~2.480GHz

# **Number of Frequency Channel**

16 channels

#### **Transmission Method**

DSSS (Direct Sequence Spread Spectrum)

#### **Modulation Method**

O-QPSK (Offset Quadrate Phase Shift Keying)

### **Radio Output Power**

+8dBm

# **Receiving Sensitivity**

-102dBm

### **Power Supply**

DC3.3V